The Application of Differential Transform Method to Solution of Linear Eight-Order Ordinary Differential Equation With Boundary Conditions.

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Abstract

In hydrodynamic and hydro magnetic it is well known that when a layer of fluid is heated from below and is subject to the action of rotation, instability may set in as over stability. This instability may be modeled by an eighth-order ordinary differential equation with appropriate boundary conditions. The differential transform method is applied to construct numerical analytic solutions of linear eight-order ordinary differential equation with two-point boundary value conditions. The difference (errors) between the series solution obtained and the exact solution is also estimated and plot of graphs showing the effectiveness of this method.

Keywords: Differential transform method, Boundary value problem System of equations, Taylor series.

1.0 Introduction

In this paper, we consider the following eight-order boundary value problem of the form;

$$y^{(v_{11})} + f(x) y(x) = g(x) \qquad a < x < b$$

(1.1)
$$y(a) = \alpha_0 \qquad y(b) = \alpha_1 \qquad y''(a) = \varepsilon_0 \qquad y''(b) = \varepsilon_1$$

$$y^{(iv)}(a) = \beta_0 \qquad y^{(iv)}(b) = \beta_1 \qquad y^{(vi)}(a) = \sigma_0 \qquad y^{(vi)}(b) = \sigma_1$$
(1.2)

Where α_i , ε_i , β_i and σ_i i = 0,1 are real constants while the function f(x) and g(x) are continuous function on the closed and bounded interval [a, b].

Eight-order ordinary differential equation arises in application of physical sciences especially in fields of engineering. A class of characteristic-value problems of higher order (as higher as twenty four) is known to arise in hydrodynamic and hydro magnetic stability [1]. In addition, it is well known that when a layer of fluid is heated from below and is subject to the action of rotation, instability may set in as over stability [1, 2, 3]. This instability may be modeled by an eighth-order ordinary differential equation with appropriate boundary conditions [1, 4].

In this paper, we shall find the solution of the above stated boundary value problem using the differential transform method. Vedat [5], studied differential transform method to linear sixth-order BVP in 2007. Agarwal [6] also studied boundary value problems for higher order differential equation in 2007. Boutayeb and Twizell [7], employed Finite difference method to find the solution of eighth order boundary value problems. The results obtained were divergent at points adjacent to the boundary. The differential transform method was also employed by Arıko[°]glu and Ozkol [8], to find the solution of difference equation. The method that we used is the differential transform methods (DTM), is based on Taylor series expansion. It was introduced by Zhou [9] in a study about electric circuits. It gives exact value of the differential transform of the *Kth* derivatives of an analytic function at a point in terms of known and unknown boundary conditions in a fast manner.

2.0 Differential Transform Method

Definition.

The differential transform of the *Kth* derivative of the function f(x) is defined as follows:

$$F(K) = \frac{1}{K!} \left[\frac{d^K f(x)}{dx^K} \right]_{x=x_0}$$
(2.1)

and the differential inverse transform of F(K) is defined as follows:

$$f(x) = \sum_{K=0}^{\infty} F(K)(x - x_0)^K$$
(2.2)

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In real application, the function f(x) is expressed as a finite series and (2.2) can be written as

$$f(x) = \sum_{K=0}^{n} F(K)(x - x_0)^K$$
(2.3)

As a result of the equations (2.1) and (2.2), defined above, some important theorems can be deduced and these theorems are used in line to obtain some basic result and computation required in illustrating this method. Equations (2.1) and (2.2) shows that this method uses the Taylor's expansion . i.e.

$$f(x) = \sum_{K=0}^{\infty} (x - x_0)^K \frac{1}{K!} \left[\frac{d^K f(x)}{dx^K} \right]_{x = x_0}$$
(2.4)

3.0 Differential Transform of Some Common Functions.

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The table 3.1 shows the differential transform of some common functions. *Table 3.1 Functions and their differential Transform*

Original functions	Transforme function
Sin(x)	$S(K) = \begin{cases} \frac{(-1)^{\frac{K-1}{2}}}{K!} & \text{if } K \text{ is odd} \\ 0, & \text{if } K \text{ is even} \end{cases}$
Cos(x)	$C(K) = \begin{cases} (-1)^{\frac{K}{2}} & \text{if } K \text{ is even} \\ \frac{K!}{0, & \text{if } K \text{ is odd}} \end{cases}$
$f(x) = e^x$	$F(K) = \frac{1}{K!}$
$f(x) = \lambda x^n$	$F(K) = \lambda \delta(K+n), where \delta(K+n) = \begin{cases} 1 & \text{if } K = n \\ 0 & \text{if } K \neq n \end{cases}$
Sin(nx)	$\lambda \text{ is a constant.}$ $S_n(K) = \begin{cases} \frac{n^K (-1)^{\frac{K-1}{2}}}{K!} & \text{if } K \text{ is odd} \end{cases}$
Cos(nx)	$C_{n}(K) = \begin{cases} \frac{n^{K}(-1)^{\frac{K}{2}}}{K!} & \text{if } K \text{ is even} \\ 0, & \text{if } K \text{ is odd} \end{cases}$
$f_n(x) = e^{nx}$	$F_n(K) = \frac{n^K}{K!}$
$f(x) = \frac{d u(x)}{dx}$	F(K) = (K+1)U(K+1)

4.0 Basic Theorems

Theorem 4.1

Suppose the differential transform of the *K*th derivative of the functions f(x), g(x), and h(x) are respectively,

$$F(K) = \frac{1}{K!} \left[\frac{d^{K} f(x)}{dx^{K}} \right]_{x=x_{0}}, \quad G(K) = \frac{1}{K!} \left[\frac{d^{K} g(x)}{dx^{K}} \right]_{x=x_{0}}, \quad H(K) = \frac{1}{K!} \left[\frac{d^{K} h(x)}{dx^{K}} \right]_{x=x_{0}},$$

If $f(x) = g(x) \pm h(x)$, then the differential transform of the *Kth* derivative of the function f(x) is given by $F(k) = G(k) \pm H(k)$

Theorem 4.2

If f(x) = cg(x), and the differential transform of the *Kth* derivative of the function g(x) is $G(K) = \frac{1}{K!} \left[\frac{d^K g(x)}{dx^K} \right]_{x=x_0}$, then the differential transform of the *Kth* derivative of the function f(x) is F(k) = c G(k), where c is a constant. **Theorem 4.3**

If $f(x) = \frac{d^n g(x)}{dx^n}$, and the differential transform of the *Kth* derivative of g(x) is $G(K) = \frac{1}{K!} \left[\frac{d^K g(x)}{dx^K} \right]_{x=x_0}$, then the differential Journal of the Nigerian Association of Mathematical Physics Volume 23 (March, 2013), 197 – 202

transform of the *K*th derivative of f(x) is given by

$$F(K) = \frac{(K+n)!}{K!}G(K+n)$$

Theorem 4.4

If f(x) = g(x)h(x), then the differential transform of the *Kth* derivative of the function f(x) is given by

$$F(K) = \sum_{k_1=0}^{K} G(K_1)H(K - K_1)$$

Theorem 4.5

If $f(x) = x^n$, then the differential transform of the *Kth* derivative of f(x) is given by

$$F(K) = \delta(K+n) \text{, where } \delta(K+n) = \begin{cases} 1 & \text{if } K = n \\ 0 & \text{if } K \neq n \end{cases}$$

Theorem 4.6

If $f(x) = g_1(x)g_2(x)\cdots g_{n-1}(x)g_n(x)$ then we define the differential transform of the *Kth* derivative of the function f(x) by

$$F(K) = \sum_{K_{n-1}=0}^{K} \sum_{K_{n-2}=0}^{K_{n-1}} \cdots \cdots \sum_{K_{2}=0}^{K} \sum_{K_{1}=0}^{K_{2}} G_{2}(K_{1})G_{1}(K_{2}-K_{1}) \times \cdots \cdots \times G_{n-1}(K_{1}-K_{2})G_{n}(K-K)$$

5.0 Numerical Results

The numerical result using the differential transform method (DTM) is then applied to the linear eight-order boundary value problem of the form of (1.1) with the boundary conditions in (1.2)

Example.

Consider the following linear boundary value problem of eight-order

$$y^{(viii)}(x) = -8e^x + y(x), \qquad 0 < x < 1$$

Subject to the boundary conditions

$$y(0) = 1, y''(0) = -1, y^{(lv)}(0) = -3, y^{(vi)}(0) = -5,$$

 $y(1) = 0, y''(1) = -2e, y^{(lv)}(1) = -4e, y^{(vl)}(1) = -6e$

Solution

Now, by transforming the equation step-wise we obtain the following: $\binom{(n)}{(n)}$

By transforming
$$y^{(viii)}(x)$$
 using theorem (4.3) we have;

$$\frac{(K+8)!}{K!}Y(K+8);$$

By transforming $-8e^x$, from the table of transformed functions, we have;

$$-\frac{8}{K!};$$

and finally by transforming y(x), by definition, we have;

Hence the total transform of the given equation becomes;

$$\frac{(K+8)!}{K!}Y(K+8) = -\frac{8}{K!} + Y(K)$$

By simplification we obtain;

$$Y(K+8) = \frac{1}{(K+1)(K+2) \times \dots \times (K+8)} \left(-\frac{8}{K!} + Y(K)\right)$$
(5.0)

This is the recurrence relations, where we obtain the value of W(0) = W(0) = W(10)

$$Y(8), Y(9), Y(10), \dots$$
 for $K = 0, 1, 2, 3, \dots$

The differential transform of the boundary conditions of the given differential equation at $x_0 = 0$ are:

$$\begin{cases} Y(0) = 1, \quad Y(2) = -\frac{1}{2}, \quad Y(4) = -\frac{1}{8}, \quad Y(6) = -\frac{1}{144}, \quad \sum_{K=0}^{n} Y(K) = 0, \\ \sum_{K=0}^{n} K(K-1)Y(K) = -2e, \quad \sum_{K=0}^{n} K(K-1)(K-2)(K-3)Y(K) = -4e \\ \sum_{K=0}^{n} K(K-1)(K-2)(K-3)(K-4)(K-5)Y(K) = -6e \end{cases}$$
(5.1)

Using the transformed boundary conditions in (5.1) we obtain the series solution as follows

$$y(x) = 1 + a_1 x - \frac{1}{2} x^2 + a_3 x^3 - \frac{1}{8} x^4 + a_5 x^5 - \frac{1}{144} x^6 + a_7 x^7 + a_8 x^8 + a_9 x^9 + a_{10} x^{10} + a_{11} x^{11} + a_{12} x^{12} + 0 x^{13}$$
(5.2)

Since $a_n = Y(n) = \frac{y^{n}(0)}{n!}$, we use the recursive relation of (5.0) to obtain the following

$$a_{8} = Y(8) = -\frac{1}{5760}; \ a_{9} = Y(9) = \left[-\frac{1}{45360} + \frac{a_{1}}{362880}\right]; \ a_{10} = Y(10) = -\frac{1}{403200}$$

$$a_{11} = Y(11) = \left[-\frac{1}{4989600} + \frac{a_{3}}{39916800}\right]; \ a_{12} = Y(12) = -\frac{1}{43545600}$$
(5.3)
for $k = 0, 1, 3, 4$, respectively.

Using the transformed boundary conditions in (5.1) for n = 12, we get Y(0) + Y(1) + Y(2) + Y(3) + Y(4) + Y(5) + Y(6) + Y(7) + Y(8) + Y(9) + Y(10) + Y(11) + Y(12) = 0 2Y(2) + 6Y(3) + 12Y(4) + 20Y(5) + 30Y(6) + 42Y(7) + 56Y(8) + 72Y(9) + 90Y(10) + 110Y(11) + 132Y(12)= -2e

24Y(4) + 120Y(5) + 360Y(6) + 840Y(7) + 1680Y(8) + 3024Y(9) + 5040Y(10) + 7920Y(11) + 11880Y(12) = -4e720Y(6) + 5040Y(7) + 20160Y(8) + 60480Y(9) + 151200Y(10) + 332640Y(11) + 665280Y(12) = -6eBy substitution of (5.3) and other known values we have

$$\begin{aligned} 1 + a_1 - \frac{1}{2} + a_3 - \frac{1}{8} + a_5 - \frac{1}{144} + a_7 - \frac{1}{5760} + \left[-\frac{1}{45360} + \frac{a_1}{362880} \right] - \frac{1}{403200} + \left[-\frac{1}{4989600} + \frac{a_3}{39916800} \right] \\ - \frac{1}{43545600} = 0 \\ -1 + 6a_3 - \frac{3}{2} + 20a_5 - \frac{1}{48} + 42a_7 - \frac{56}{5760} + \left[-\frac{72}{45360} + \frac{72a_1}{362880} \right] - \frac{90}{403200} + \left[-\frac{110}{4989600} + \frac{110a_3}{39916800} \right] \\ - \frac{132}{43545600} = -2e \\ -3 + 120a_5 + -\frac{360}{344} + 840a_7 - \frac{1680}{5760} + \left[-\frac{3024}{45360} + \frac{3024a_1}{362880} \right] - \frac{5040}{403200} + \left[-\frac{7920}{4989600} + \frac{7920a_3}{39916800} \right] + -\frac{11880}{43545600} \\ = -4e \\ - \frac{720}{144} + 5040a_7 - \frac{20160}{5760} + \left[-\frac{60480}{45360} + \frac{60480a_1}{362880} \right] - \frac{151200}{403200} + \left[-\frac{332640}{4989600} + \frac{332640a_3}{39916800} \right] - \frac{665280}{43545600} = -6e \\ So that by simplifying we obtain the following system of equations \\ \frac{329500910}{5040} a_3 + a_5 + a_7 = -0.367857195 \\ \frac{329500910}{5040} a_3 + 20a_5 + 42a_7 = -2.716672508 \\ \frac{3024}{322860} a_1 + \frac{39916800}{39916800} a_3 + 20a_5 + 42a_7 = -4.966331678 \\ \frac{60480}{362880} a_1 + \frac{39916800}{39916800} a_3 + 5040a_7 = -6.019413191 \\ \text{Then by solving for } a_{1,a_3,a_5,a_7} we obtain the following values \\ a_1 = -6.771 \times 10^{-7}, a_3 = -0.3333344127, a_5 = -0.03332858585, a_7 = -0.00119054874 \\ x_7 = -0.00119054874 \\ y(x) = 1 - 6.771 \times 10^{-7}, -\frac{1}{2}x^2 - 0.3333344127x^3 - \frac{1}{8}x^4 - 0.03332858585x^5 - \frac{1}{144}x^6 - 0.00119054874x^7 \\ - \frac{1}{5760}x^8 - 2.20458 \times 10^{-5}x^9 - \frac{1}{1403200}x^{10} - 2.50503 \times 10^{-7}x^{11} - \frac{1}{43545600}x^{12} + 0x^{13} \\ \text{The nebring a brained with the alex contrastice of the RVB nitrom of the RVB nitrom$$

This solution obtained can be compared with the closed exact solution of the BVP given which is $y(x) = (1 - x)e^x$. The table below gives the comparison.

x	Series solution	Exact solution	Error
0.0	1	1	0.0000000
0.2	0.9771221	0.9771222	1.4390394×10^{-7}
0.4	0.8950945	0.8950948	3.3517633×10^{-7}
0.6	0.7288469	0.7288475	6.0443279×10^{-7}
0.8	0.4451072	0.4451082	9.516282×10^{-7}
1.0	0.0000000	0.0000000	0.0000000

Table 5.1 Differences between series solution obtained and exact solution

Error = *Exact Solution* - *Series Solution*

Table 5.1 exhibits the numerical values for series solution and that of the exact solution along with the errors obtained. We observed that the errors are minimal. By using the DTM, It is obvious that the errors can be reduced further and higher accuracy can be obtained by evaluating more components of y(x).

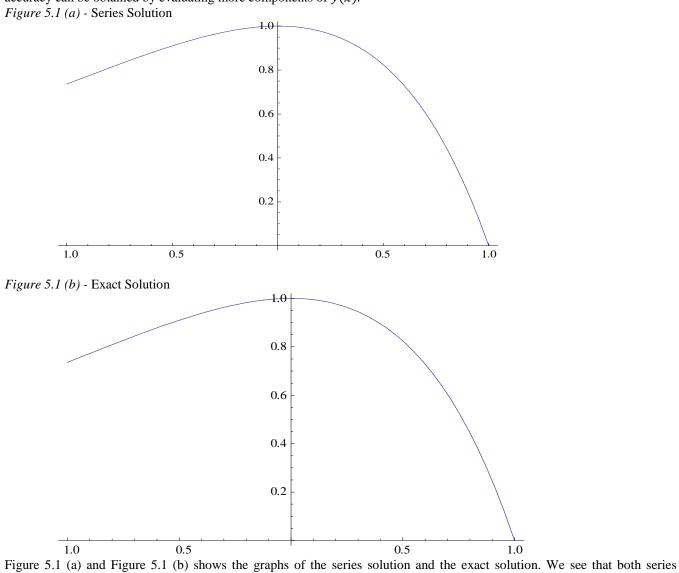


Figure 5.1 (a) and Figure 5.1 (b) shows the graphs of the series solution and the exact solution. We see that both series solution obtained by the differential transform method and the exact solution are almost the same with nearly insignificant difference (error).

6.0 Conclusion

In this paper, we studied differential transform method for solving linear ordinary differential equation of eight-order with boundary conditions. This method was applied to solve some boundary value problems. In the Example, we obtained the exact series solution for the BVP. It is observed that the method is an effective and reliable tool for the solution of such problems.

It may be concluded that Differential Transform Method (DTM) is very powerful and efficient in finding the analytic solutions for a wide class of boundary value problems. The method gives more realistic series solutions that converge very rapidly in physical problems. Thus we conclude that differential transform method can be considered as an efficient method for solving linear BVP.

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