

## Comparison of second and third orders Runge-Kutta methods for solving initial-value problems in ordinary differential equations

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### Abstract

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*This work is concerned with the analysis of second and third orders Runge-Kutta formulae capable of solving initial value problems in Ordinary Differential Equations of the form:  $y' = f(x, y)$ ,  $y(x_0) = y_0$ ,  $a \leq x \leq b$ . The intention is to find out which of these two orders can improve the performance of results when implemented on the initial-value problems defined above. We found out that the higher the order, the better the performance of that order. When parameters are properly varied, performance may also improve.*

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### 1.0 Introduction

The object of this research work is to use Runge-Kutta Methods to solve initial value problems in Ordinary Differential Equations of the form:  $y' = f(x, y)$ ,  $y(x_0) = y_0$ ,  $a \leq x \leq b$ , with a view to finding out its consistency and convergence.

In the work of Lambert [1], the Runge-Kutta Methods represent an important family of implicit and explicit iterative methods for approximation of ordinary differential equations in numerical analysis. Furthermore, of all computational methods for the numerical solution of initial-value problems, the easiest to implement is Euler's rule. It is explicit and, being a one-step method, requires no additional starting values and readily permits a change of step length during the computation. Its low order, of course, makes it of limited practical value. Linear multi-step methods achieve higher order by sacrificing the one-step nature of the algorithm, while retaining linearity with respect to  $y_{n+j}, f_{n+j}, j = 0, 1, \dots, k$ . Higher order can also be achieved by sacrificing linearity, but preserving the one-step nature of the algorithm.

Thus, the philosophy behind the Runge-Kutta method is to retain the advantages of one-step methods. Due to the loss of linearity, error analysis is considerably more difficult than in the case of linear multi-step methods. Traditionally, Runge-Kutta methods are all explicit, although, recently, implicit Runge-Kutta Method, which have improved weak stability characteristics, have been considered.

We shall use the phrase "Runge-Kutta Method" to mean explicit Runge-Kutta Method. Thus, a Runge-Kutta method may be regarded as a particular case of the general explicit one-step method of the kind:

$$y_{n+1} - y_n = h \Phi(x_n, y_n; h). \tag{1.1}$$

### 1.1 The statement of the problem

We are interested in solving the general initial-value problem:

$$y' = f(x, y), y(x_0) = y_0, a \leq x \leq b, y(0) \text{ (given)} \tag{1.2}$$

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(Whose gradient function  $f(x, y)$  may have points of discontinuities in a differential system called points of singularities).

## 2.0 The second-order Runge-Kutta methods

The general R-stage Runge-Kutta method is:

$$\begin{aligned}
 y_{n+1} - y_n &= h\phi(x_n, y_n; h), \\
 \phi(x_n, y_n; h) &= \sum_{r=1}^R c_r k_r, \\
 k_1 &= f(x, y), \\
 k_r &= f(x + ha_r, y + h \sum_{s=1}^{r-1} b_{rs} k_s), \quad r = 2, 3, \dots, R, \\
 a_r &= \sum_{s=1}^{r-1} b_{rs}, \quad r = 2, 3, \dots, R
 \end{aligned} \tag{2.3}$$

Now, for the case  $R = 2$ , we shall have:

$$\begin{aligned}
 k_1 &= hf(x_n, y_n) \\
 k_2 &= hf(x_n + a_2 h, y_n + hb_{21} k_1)
 \end{aligned} \tag{2.4}$$

and  $y_{n+1} = y_n + c_1 k_1 + c_2 k_2$ , where the parameters  $a_2, b_{21}, c_1$  and  $c_2$  are chosen to make  $y_{n+1}$  close to  $y(x_{n+1})$ ,  $k_1 = hf_n$ . Expanding  $k_2$  as a Taylor's series about the point  $(x, y)$  we have:

$$\begin{aligned}
 k_2 &= hf(x_n + a_2 h, y_n + b_{21} hf_n) = h[f(x_n, y_n) + (a_2 hf_x + b_{21} hf_y) + \frac{1}{2!}(a_2^2 h^2 f_{xx} + 2a_2 b_{21} h^2 f_{xy} + b_{21}^2 h^2 f_{yy}) + \dots] \\
 k_{2n} &= hf_n + h^2(a_2 f_x + b_{21} f_y) + h^3/2(a_2^2 f_{xx} + 2a_2 b_{21} f_{xy} + b_{21}^2 f_{yy}) + \dots
 \end{aligned}$$

Substituting the value of  $k_1$  and  $k_2$  into equation (2.2), we get,

$$y_{n+1} = y_n + (c_1 + c_2)hf_n + h^2(a_2 c_2 f_x + b_{21} c_2 f_y) + h^3/2(c_2(a_2^2 f_{xx} + 2a_2 b_{21} f_{xy} + b_{21}^2 f_{yy})) + \dots \tag{2.5}$$

The Taylor's series about the point  $(x, y)$  is:

$$y(x_{n+1}) = y(x_n) + hy'(x_n) + h^2/2! y''(x_n) + h^3/3! y'''(x_n) + \dots \tag{2.6}$$

where,

$$\begin{aligned}
 y' &= f(x, y) \\
 y'' &= f'_x = f_x + f_y y' = f_x + f_y f_x \\
 y''' &= f'' = f_{xx} + f_{xy} f' + f_{yx} f' + f_{yy} f'^2 + f_{yx} f_x + f_y^2 = f_{xx} + 2f_{xy} f' + f_{yy} f'^2 + f_{yx} f_x + f_y^2 f \\
 y^{(iv)} &= f^{(iv)} = f_{xxx} + 3ff_{xxy} + 3f^2 f_{xyy} + 3f_x f_{xy} + 5ff_{xy} f_y + 3ff_x f_{yy} + f_{xy} f_y + 4f^2 f_{xy} f_y + f_{xy} f_y^2 + ff_y^3 + f^3 f_{yyy} \\
 y^{(v)} &= f^{(v)} = f_{xxx} + 4ff_{xxy} + 6f^2 f_{xyy} + 6f_x f_{xy} + 9ff_{xy} f_y + 4f^2 f_{xy} f_y + 6f_{xx} f_{xy} + 15f^2 f_{xy} f_y + 6ff_x f_{xy} + 4f_{xy} f_y + 8ff^2 f_{xy} + 8f^2 f_{xy} f_y + 7f_x f_y + 9ff_{xy} f_y^2 + 6f^2 f_{xy} f_y + 4ff_{xx} f_y + 3f_x^2 f_{yy} + 13ff_x f_y f_y + f_{xx} f_y + 7f^3 f_y f_{yyy} + 4f^3 f_y^2 + 4f^2 f_{xy} f_y + 11f^2 f_y^2 f_y + f_{xy} f_y^2 + f_x f_y^2 + f_x f_y^3 + ff_y^4 + f^4 f_{yyy},
 \end{aligned}$$

where  $f_x, f_y$  represent the derivatives of  $f$  with respect to  $x, y$  respectively.

Comparing equations (2.5) and (2.6) and matching coefficients of powers of  $h$ , we obtain three equations for the parameters,

$$\begin{aligned}
 c_1 + c_2 &= 1 \\
 a_2 c_2 &= 1/2 \\
 b_{21} c_2 &= 1/2
 \end{aligned} \tag{2.7}$$

From these equations, we see that if  $c_2$  is chosen arbitrarily (non zero), then

$$b_{21} = a_2, \quad c_2 = 1/2a_2, \quad c_1 = 1 - 1/2a_2 \tag{2.8}$$

using (2.8) and (2.5), we get

$$y_{n+1} = y_n + hf_n + h^2/2(f_x + f_y f_n) + c_2 h^3/4(f_{xx} + 2f_{xy} f_n + f_n^2 f_{yy}) + \dots \tag{2.9}$$

Subtracting (2.9) from (2.5), we obtain the local truncation error

$$\begin{aligned}
 T_n &= y(x_{n+1}) - y_{n+1} \\
 T_n &= h^3[(1/6 - a_2/4)(f_{xx} + 2f_{xy} f_n + f_n^2 f_{yy}) + 1/6 f_y (f_x + f_n f_y)] + \dots
 \end{aligned}$$

We observe that no choice of the parameter  $a_2$  will make the leading term  $T_n$  vanish for all  $f(x, y)$ . The local truncation error depends not only on derivatives of the solution  $y(x)$  but also

on the function  $f$ . This is typical of all Runge-Kutta methods, in most other methods the truncation error depends only on certain derivatives of  $y(x)$ . Generally,  $a_2$  will be chosen between 0 and 1. Sometimes, the free parameters are chosen either to have as large as possible the interval of absolute stability or to minimize the sum of the absolute values of the coefficients in the term  $T_n$ . Such a choice is called optimal.

Thus, we state the second order Runge-Kutta methods by listing the coefficients as follows:

	$a_2, b_{21}$	
		$c_1, c_2$
(a)	$1/2, 1/2$	$0, 1$
(b).	$2/3, 2/3$	$1/4, 3/4$
(c).	$1, 1$	$1/2, 1/2$

These give the following formulae respectively:

- (a)  $k_1 = hf(x_n, y_n)$   
 $k_2 = hf(x_n + 1/2h, y_n + 1/2k_1)$   
 $y_{n+1} = y_n + k_2$
- (b)  $k_1 = hf(x_n, y_n)$   
 $k_2 = hf(x_n + 2/3h, y_n + 2/3k_1)$   
 $y_{n+1} = y_n + 1/4k_1 + 3/4k_2$
- (c)  $k_1 = hf(x_n, y_n)$   
 $k_2 = hf(x_n + h, y_n + k_1)$   
 $y_{n+1} = y_n + 1/2k_1 + 1/2k_2$

### 2.1 The third-order Runge-Kutta methods

We shall consider the derivation of a third order Runge-Kutta method. With reference to Lambert [1] and Jain [2], the third-order Runge-Kutta Method is derived thus:

At the stage,  $R = 3$ . The method is derived from the general Runge-Kutta formula defined above.

Hence,

$$\begin{aligned} \phi(x_n, y_n, h) &= c_1k_1 + c_2k_2 + c_3k_3 \\ k_1 &= f(x_n, y_n), \end{aligned} \tag{2.10}$$

and  
Thus,  
with

$$\begin{aligned} k_2 &= f(x_n + ha_2, y_n + h(b_{21}k_1)) \\ k_3 &= f(x_n + ha_3, y_n + h(b_{31}k_1 + b_{32}k_2)) \\ a_2 = b_{21}, a_3 = b_{31} + b_{32} &\Rightarrow b_{31} = a_3 - b_{32} \\ y_{n+1} - y_n &= h(c_1k_1 + c_2k_2 + c_3k_3) \\ k_1 &= f(x_n, y_n) \\ k_2 &= f(x_n + ha_2, y_n + ha_2k_1) \end{aligned} \tag{2.11}$$

and

$$k_3 = f(x_n + ha_3, y_n + h(a_3 - b_{32})k_1 + hb_{32}k_2)$$

Expanding  $k_2$  as a Taylor's series about the point  $(x, y)$  we have:

$$k_2 = \sum_{r=0}^{\infty} \frac{1}{r!} \left[ ha_2 \frac{\partial}{\partial x} + ha_2k_1 \frac{\partial}{\partial x} \right]^r f(x, y)$$

Hence,  $k_2 = f + ha_2(f_x + k_1f_y) + h^2/2a_2^2(f_{xx} + 2k_1f_{xy} + k_1^2f_{yy}) + 0(h^3)$ . Similarly,

$$k_3 = \sum_{r=0}^{\infty} \frac{1}{r!} \left[ \left( ha_3 \frac{\partial}{\partial x} + h[(a_3 - b_{32})k_1 + hb_{32}k_2] \frac{\partial}{\partial x} \right)^r f(x, y) \right]$$

$$k_3 = f(x_n, y_n) + ha_3 \frac{\partial}{\partial x} f(x_n, y_n) + h[(a_3 - b_{32})k_1 + hb_{32}k_2] \frac{\partial}{\partial x} f(x_n, y_n) + \frac{1}{2} [ha_3 \frac{\partial}{\partial x} + h[(a_3 - b_{32})k_1 + hb_{32}k_2] \frac{\partial}{\partial x}]^2 \frac{\partial^2}{\partial x \partial y} f(x_n, y_n) + 0(h^3)$$

$$k_3 = f(x_n, y_n) + h[a_3 f_x + [(a_3 - b_{32})k_1 b_{32} k_2] f_y] + \frac{h^2}{2} [a_3^2 f_{xx} + a_3 [(a_3 - b_{32})k_1 + b_{32}k_2] f_{xy} + [(a_3 - b_{32})k_1 + b_{32}k_2]^2 f_{yy}] + 0(h^3)$$

substituting  $k_1, k_2$  and  $k_3$  into equation (2.8), we have  $\phi(x_n, y_n, h) = c_1 k_1 + c_2 k_2 + c_3 k_3$  becoming,  
 $y_{n+1} - y_n = h(c_1 a_1 + c_2 a_2 + c_3 a_3) f + h^2 (c_2 a_2 + c_3 a_3) f_x + h^2 (c_2 a_2 k_1 + c_3 a_3 k_1) f_y + \frac{1}{2} h^3 [c_2 a_3^2 + c_3 a_3^2 k_1^2 - 2c_3 a_3 b_{32} k_1^2 + 2c_2 a_2 b_{32} k_1^2 - c_3 b_{32}^2 k_1^2 + c_2 b_{32}^2 k_1^2] f_{yy} + 0(h^4)$  (2.12)

Now, comparing this with the Taylor's series expansion for order 3, we have,  
 $y(x_n) - y(x_0) = hk_1 + h^2/2 f_x + h^2/2 k_1 f_y + h^3/6 f_{xx} + h^3/6 f_x f_y + h^3/3 k_1 f_{xy} + h^3/6 k_1 f_y^2 + h^3/6 k_1^2 f_{yy}$  (2.13)  
 by equating coefficients, we have

$$\begin{aligned} c_1 + c_2 + c_3 &= 1 \\ c_2 a_2 + c_3 a_3 &= \frac{1}{2} \\ c_2 a_3^2 + c_3 a_3^2 &= \frac{1}{3} \\ c_3 a_2 b_{32} &= \frac{1}{6} \end{aligned} \quad (2.14)$$

To this, we have four equations in six unknowns and there exists two parameter family of solutions.

This two particular solutions lead to well-known third order Runge-Kutta Methods.

(a)  $c_1 = 1/4, c_2 = 0, c_3 = 3/4, a_2 = 1/3, a_3 = 2/3, b_{32} = 2/3$ . The resulting method may be written:

$$\begin{aligned} y_{n+1} - y_n &= \frac{h}{4} (k_1 + 3k_3), \\ k_1 &= f(x_n, y_n), \\ k_2 &= f(x_n + \frac{1}{3}h, y_n + \frac{1}{3}hk_1) \\ k_3 &= f(x_n + \frac{2}{3}h, y_n + \frac{2}{3}hk_2) \end{aligned} \quad (2.15)$$

Equation (2.15) is known as the Heun's third-order formula. We observe that the computational advantages in choosing  $c_2 = 0$  is somewhat illusory since, although  $k_2$  does not appear in the first equation of equation(s). It must nevertheless be calculated at each step.

(b)  $c_1 = 1/6, c_2 = 2/3, c_3 = 1/6, a_2 = 1/2, a_3 = 1, b_{32} = 2$ . The resulting method,

$$\begin{aligned} y_{n+1} - y_n &= \frac{h}{6} (k_1 + 4k_3 + k_3), \\ k_1 &= f(x_n, y_n), \\ k_2 &= f(x_n + \frac{1}{2}h, y_n + \frac{1}{2}hk_1) \\ k_3 &= f(x_n + h, y_n - hk_1 + 2hk_2) \end{aligned} \quad (2.16)$$

is Kutta's third-order rule. It is the most popular third-order Runge-Kutta Method for desk computation (largely because the coefficient  $1/2$  is preferable to  $1/3$ , which appears frequently in equation (2.15)).

### 3.0 Numerical computations and results

In order to access the performance of the second and third orders Runge-Kutta methods, the following sample problems were solved:

(i)  $y' = 1 + y^2, y(0) = 1, 0 \leq x \leq 1$ , whose theoretical solution is:  $y(x) = \tan(x + \frac{\pi}{4})$

(ii)  $y' = -y, y(0) = 1, 0 \leq x \leq 1$ , whose theoretical solution is:  $y(x) = 1/\exp x$

(iii)  $y' = y, y(0) = 1, 0 \leq x \leq 1$ , whose theoretical solution is:  $y(x) = \exp x$

(iv)  $y' = y^2, y(0) = 1, 0 \leq x \leq 1$ , whose theoretical solution is:  $y(x) = 1/1-x$

### 3.1 Tables of results

#### Order 2 Problem 1

XN	YN	TSOL	ERROR
.1D+00	0.1222000000000D+01	0.1223048880450D+01	0.1048880449865D-02
.2D+00	0.1504904563032D+01	0.1508497647121D+01	0.3593084089073D-02
.3D+00	0.1885838780962D+01	0.1895765122854D+01	0.9926341892099D-02
.4D+00	0.2437784037299D+01	0.2464962756723D+01	0.2717871942365D-01
.5D+00	0.3325414563118D+01	0.3408223442336D+01	0.8280887921824D-01
.6D+00	0.5004946244862D+01	0.5331855223459D+01	0.3269089785964D+00
.7D+00	0.9252945637605D+01	0.1168137380031D+02	0.2428428162705D+01
.8D+00	0.2968052273478D+02	-.6847966834558D+02	-.9816019108036D+02
.9D+00	0.7685396051645D+03	-.8687629546482D+01	-.7772272347110D+03
.1D+01	0.1790353923463D+09	-.4588037824984D+01	-.1790353969344D+09

#### Order 3 Problem 1

XN	YN	TSOL	ERROR
.1D+00	0.1222901142387D+01	0.1223048880450D+01	0.1477380630341D-03
.2D+00	0.1507980352553D+01	0.1508497647121D+01	0.5172945686114D-03
.3D+00	0.1894251391813D+01	0.1895765122854D+01	0.1513731041409D-02
.4D+00	0.2460382773866D+01	0.2464962756723D+01	0.4579982856682D-02
.5D+00	0.3391873333485D+01	0.3408223442336D+01	0.1635010885070D-01
.6D+00	0.5248451742415D+01	0.5331855223459D+01	0.8340348104371D-01
.7D+00	0.1069156363364D+02	0.1168137380031D+02	0.9898101666695D+00
.8D+00	0.5993762963300D+02	-.6847966834558D+02	-.1284172979786D+03
.9D+00	0.3675614567764D+06	-.8687629546482D+01	-.3675701444059D+06
.1D+01	0.1371434973316D+36	-.4588037824984D+01	-.1371434973316D+36

#### Order 2 Problem 2

XN	YN	TSOL	ERROR
.1D+00	0.9050000000000D+00	0.9048374180360D+00	-.1625819640404D-03
.2D+00	0.8190250000000D+00	0.8187307530780D+00	-.2942469220182D-03
.3D+00	0.7412176250000D+00	0.7408182206817D+00	-.3994043182819D-03
.4D+00	0.6708019506250D+00	0.6703200460356D+00	-.4819045893606D-03
.5D+00	0.6070757653156D+00	0.6065306597126D+00	-.5451056029917D-03
.6D+00	0.5494035676106D+00	0.5488116360940D+00	-.5919315166144D-03
.7D+00	0.4972102286876D+00	0.4965853037914D+00	-.6249248962205D-03
.8D+00	0.4499752569623D+00	0.4493289641172D+00	-.6462928450836D-03
.9D+00	0.4072276075509D+00	0.4065696597406D+00	-.6579478102870D-03
.1D+01	0.3685409848336D+00	0.3678794411714D+00	-.6615436621096D-03

#### Order 3 Problem 2

XN	YN	TSOL	ERROR
.1D+00	0.9048333333333D+00	0.9048374180360D+00	0.4084702626250D-05
.2D+00	0.8187233611111D+00	0.8187307530780D+00	0.7391966870607D-05
.3D+00	0.7408081879120D+00	0.7408182206817D+00	0.1003276968092D-04
.4D+00	0.6703079420291D+00	0.6703200460356D+00	0.1210400656437D-04
.5D+00	0.6065169695460D+00	0.6065306597126D+00	0.1369016665864D-04
.6D+00	0.5487967712775D+00	0.5488116360940D+00	0.1486481651014D-04
.7D+00	0.4965696118776D+00	0.4965853037914D+00	0.1569191380352D-04
.8D+00	0.4493127371473D+00	0.4493289641172D+00	0.1622696996778D-04
.9D+00	0.4065531416621D+00	0.4065696597406D+00	0.1651807852571D-04
.1D+01	0.3678628343472D+00	0.3678794411714D+00	0.1660682420951D-04

**Order 2 Problem 3**

XN	YN	TSOL	ERROR
.1D+00	0.1105000000000D+01	0.1105170918076D+01	0.1709180756475D-03
.2D+00	0.1221025000000D+01	0.1221402758160D+01	0.3777581601698D-03
.3D+00	0.1349232625000D+01	0.1349858807576D+01	0.6261825760028D-03
.4D+00	0.1490902050625D+01	0.1491824697641D+01	0.9226470162702D-03
.5D+00	0.1647446765941D+01	0.1648721270700D+01	0.1274504759503D-02
.6D+00	0.1820428676364D+01	0.1822118800391D+01	0.1690124026118D-02
.7D+00	0.2011573687383D+01	0.2013752707470D+01	0.2179020087825D-02
.8D+00	0.2222788924558D+01	0.2225540928492D+01	0.2752003934638D-02
.9D+00	0.2456181761636D+01	0.2459603111157D+01	0.3421349520548D-02
.1D+01	0.2714080846608D+01	0.2718281828459D+01	0.4200981850821D-02

**Order 3 Problem 3**

XN	YN	TSOL	ERROR
.1D+00	0.1105166666667D+01	0.1105170918076D+01	0.4251408980860D-05
.2D+00	0.1221393361111D+01	0.1221402758160D+01	0.9397049058668D-05
.3D+00	0.1349843229588D+01	0.1349858807576D+01	0.1557798803975D-04
.4D+00	0.1491801742566D+01	0.1491824697641D+01	0.2295507497307D-04
.5D+00	0.1648689559160D+01	0.1648721270700D+01	0.3171154060877D-04
.6D+00	0.1822076744464D+01	0.1822118800391D+01	0.4205592604678D-04
.7D+00	0.2013698482091D+01	0.2013752707470D+01	0.5422537983479D-04
.8D+00	0.2225472439124D+01	0.2225540928492D+01	0.6848936862669D-04
.9D+00	0.2459517957305D+01	0.2459603111157D+01	0.8515385191776D-04
.1D+01	0.2718177262482D+01	0.2718281828459D+01	0.1045659774341D-03

**Order 2 Problem 4**

XN	YN	TSOL	ERROR
.1D+00	0.1110500000000D+01	0.1111111111111D+01	0.6111111111111D-03
.2D+00	0.1248276228587D+01	0.1250000000000D+01	0.1723771413397D-02
.3D+00	0.1424760126021D+01	0.1428571428571D+01	0.3811302550067D-02
.4D+00	0.1658736394656D+01	0.1666666666667D+01	0.7930272010906D-02
.5D+00	0.1983300735783D+01	0.2000000000000D+01	0.1669926421672D-01
.6D+00	0.2462397829859D+01	0.2500000000000D+01	0.3760217014070D-01
.7D+00	0.3236425671191D+01	0.3333333333333D+01	0.9690766214193D-01
.8D+00	0.4677725672023D+01	0.5000000000000D+01	0.3222743279767D+00
.9D+00	0.8128767717881D+01	0.1000000000000D+02	0.1871232282119D+01

**Order 3 Problem 4**

XN	YN	TSOL	ERROR
.1D+00	0.1111057827572D+01	0.1111111111111D+01	0.5328353909473D-04
.2D+00	0.1249840436239D+01	0.1250000000000D+01	0.1595637609275D-03
.3D+00	0.1428192621392D+01	0.1428571428571D+01	0.3788071794708D-03
.4D+00	0.1665807462331D+01	0.1666666666667D+01	0.8592043360645D-03
.5D+00	0.1997985670073D+01	0.2000000000000D+01	0.2014329926953D-02
.6D+00	0.2494791095604D+01	0.2500000000000D+01	0.5208904395528D-02
.7D+00	0.3317137851229D+01	0.3333333333333D+01	0.1619548210399D-01
.8D+00	0.4929048284012D+01	0.5000000000000D+01	0.7095171598811D-01
.9D+00	0.9343550594338D+01	0.1000000000000D+02	0.6564494056619D+00

The computer program for the results in this paper can be found in the appendix.

**4.0 Findings**

After the implementation of the second and third orders Runge-Kutta formulae on some selected initial-value problems, it was discovered from our tables of results that the third-

order Runge-Kutta formula has higher accuracy from the error column, the accuracy and effectiveness of the third-order formula is also seen.

One can say that the higher the order (R), the higher the accuracy of that order. But when parameters are changed to high grade, the formula may produce more accurate results. We also found out that when we compared our expansion with the Taylor series expansion, we got some non-linear equations.

The parameters in these non-linear equations exceed the number of equations but in the work of Lambert [1], these parameters are chosen to ensure that the method has:

- (i) Adequate order of accuracy
- (ii) Minimum bound of local truncation error
- (iii) Minimum computer storage facilities.

## 5.0 Conclusion

Finally, it is clear that the survey carried out is of high value to see the effectiveness and accuracy of the second-order and third-order Runge-Kutta formulae in handling initial-value problems in Ordinary Differential Equations. This analysis proved that when the method is of higher order, it may likely produce more effective and accurate results if parameters are properly varied.

### 5.1 Summary

Summarily, our  $k_{i,s}$  were expanded by Taylor series expansion about the point  $(x_n, y_n)$ . These expansions are inserted into  $\phi(x_n, y_n; h)$  and compared with the Taylor series expansion of  $\phi(x_n, y_n; h)$ . This comparison resulted in some non-linear equations whose parameters were chosen to ensure that the equations were satisfied.

Hence, the Runge-Kutta method as a single step method has shown that no area of research is over exhausted depending on the area of interest.

## APPENDIX

### FORTRAN PROGRAMS THAT GENERATED THE RESULTS.

```

C PRO
C SECOND-ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=1+Y**2,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=TAN(XN+PI/4)
DOUBLE PRECISION XN,YN,H,PI,ONE,TWO,FOUR
DOUBLE PRECISION TSOL,ERROR,K1,K2
OPEN(6,FILE='RUNG2.OUT')
H=0.1D0
YN=1.0D0
XN=0.1D0
ONE=1.0D0
TWO=2.0D0
FOUR=4.0D0
PI=FOUR*DATAN(ONE)
WRITE(6,101)
3   K1=ONE+YN**2
    K2=ONE+(YN+H*K1)**2
    YN=YN+H/TWO*(K1+K2)
    TSOL=TAN(XN+(PI/FOUR))
    ERROR=TSOL-YN
    WRITE(6,100)XN,YN,TSOL,ERROR
    XN=XN+H
    IF(XN.LE.ONE) GOTO 3
100 FORMAT(D6.1,1X,3(3X,D19.13))
101 FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
END
C PRO
C THIRD- ORDER RUNGE-KUTTA METHOD

```

```

C OUR PROBLEM IS :Y'=1+Y**2,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=TAN(XN+PI/4)
  DOUBLE PRECISION XN,YN,H,PI,ONE,THREE,TWO,FOUR
  DOUBLE PRECISION TSOL,ERROR,K1,K2,K3
  OPEN(6,FILE='RUNG2.OUT')
  H=0.1D0
  YN=1.0D0
  XN=0.1D0
  HALF=0.5D0
  THREE=3.0D0
  ONE=1.0D0
  TWO=2.0D0
  FOUR=4.0D0
  PI=FOUR*DATAN(ONE)
  WRITE(6,101)
3   K1=ONE+YN**2
   K2=ONE+(YN+(H/THREE)*K1)**2
   K3=ONE+(YN+(H/THREE)*TWO*K2)**2
   YN=YN+H/FOUR*(K1+THREE*K3)
   TSOL=TAN(XN+(PI/FOUR))
   ERROR=TSOL-YN
   WRITE(6,100)XN,YN,TSOL,ERROR
   XN=XN+H
   IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
      END

```

```

C PRO
C SECOND-ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=-Y,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=1/EXP(XN)
  DOUBLE PRECISION XN,YN,H,ONE,TWO
  DOUBLE PRECISION TSOL,ERROR,K1,K2
  OPEN(6,FILE='RUNG2.OUT')
  H=0.1D0
  YN=1.0D0
  XN=0.1D0
  ONE=1.0D0
  TWO=2.0D0
  WRITE(6,101)
3   K1=-YN
   K2=-(YN+H*K1)
   YN=YN+H/TWO*(K1+K2)
   TSOL=ONE/EXP(XN)
   ERROR=TSOL-YN
   WRITE(6,100)XN,YN,TSOL,ERROR
   XN=XN+H
   IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
      END

```

```

C PRO
C THIRD- ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=-Y,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=1/EXP(XN)
  DOUBLE PRECISION XN,YN,H,ONE,THREE,TWO,FOUR
  DOUBLE OPEN(6,FILE='RUNG2.OUT')
  PRECISION TSOL,ERROR,K1,K2,K3
  H=0.1D0
  YN=1.0D0
  XN=0.1D0
  HALF=0.5D0
  THREE=3.0D0

```

```

ONE=1.0D0
TWO=2.0D0
FOUR=4.0D0
WRITE(6,101)
3   K1=-YN
    K2=-(YN+(H/THREE)*K1)
    K3=-(YN+(H/THREE)*TWO*K2)
    YN=YN+H/FOUR*(K1+THREE*K3)
    TSOL=ONE/EXP(XN)
    ERROR=TSOL-YN
    WRITE(6,100)XN,YN,TSOL,ERROR
    XN=XN+H
    IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
END

```

```

C PRO
C SECOND-ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=Y,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=EXP(XN)
  DOUBLE PRECISION XN,YN,H,ONE,TWO
  DOUBLE PRECISION TSOL,ERROR,K1,K2
  OPEN(6,FILE='RUNG2.OUT')
  H=0.1D0
  YN=1.0D0
  XN=0.1D0
  ONE=1.0D0
  TWO=2.0D0
  WRITE(6,101)
3   K1=YN
    K2=(YN+H*K1)
    YN=YN+H/TWO*(K1+K2)
    TSOL=EXP(XN)
    ERROR=TSOL-YN
    WRITE(6,100)XN,YN,TSOL,ERROR
    XN=XN+H
    IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
END

```

```

C PRO
C THIRD- ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=Y,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=EXP(XN)
  DOUBLE PRECISION XN,YN,H,ONE,THREE,TWO,FOUR
  DOUBLE PRECISION TSOL,ERROR,K1,K2,K3
  OPEN(6,FILE='RUNG2.OUT')
  H=0.1D0
  YN=1.0D0
  XN=0.1D0
  HALF=0.5D0
  THREE=3.0D0
  ONE=1.0D0
  TWO=2.0D0
  FOUR=4.0D0
  WRITE(6,101)
3   K1=YN
    K2=(YN+(H/THREE)*K1)
    K3=(YN+(H/THREE)*TWO*K2)
    YN=YN+H/FOUR*(K1+THREE*K3)
    TSOL=EXP(XN)
    ERROR=TSOL-YN
    WRITE(6,100)XN,YN,TSOL,ERROR
    XN=XN+H

```

```

        IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
      END

```

```

C PRO
C SECOND-ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=Y**2,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=1/(1-X)
      DOUBLE PRECISION XN,YN,H,ONE,TWO
      DOUBLE PRECISION TSOL,ERROR,K1,K2
      OPEN(6,FILE='RUNG2.OUT')
      H=0.1D0
      YN=1.0D0
      XN=0.1D0
      ONE=1.0D0
      TWO=2.0D0
      WRITE(6,101)
3     K1=YN**2
      K2=(YN+H*K1)**2
      YN=YN+H/TWO*(K1+K2)
      TSOL=ONE/(ONE-XN)
      ERROR=TSOL-YN
      WRITE(6,100)XN,YN,TSOL,ERROR
      XN=XN+H
      IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
      END

```

```

C PRO
C THIRD- ORDER RUNGE-KUTTA METHOD
C OUR PROBLEM IS :Y'=Y**2,Y(O)=1
C THEORETICAL SOLUTION:Y(XN)=1/(1-X)
      DOUBLE PRECISION XN,YN,H,ONE,THREE,TWO,FOUR
      DOUBLE PRECISION TSOL,ERROR,K1,K2,K3
      OPEN(6,FILE='RUNG2.OUT')
      H=0.1D0
      YN=1.0D0
      XN=0.1D0
      HALF=0.5D0
      THREE=3.0D0
      ONE=1.0D0
      TWO=2.0D0
      FOUR=4.0D0
      WRITE(6,101)
3     K1=YN**2
      K2=(YN+(H/THREE)*K1)**2
      K3=(YN+(H/THREE)*TWO*K2)**2
      YN=YN+H/FOUR*(K1+THREE*K3)
      TSOL=ONE/(ONE-XN)
      ERROR=TSOL-YN
      WRITE(6,100)XN,YN,TSOL,ERROR
      XN=XN+H
      IF(XN.LE.ONE) GOTO 3
100  FORMAT(D6.1,1X,3(3X,D19.13))
101  FORMAT(2X,'XN',13X,'YN',16X,'TSOL',16X,'ERROR')
      END

```

### *References*

- [1] Lambert, J.D (1973); "Computer Methods in ODE's", John Wiley Publications, New York.
- [2] Jain, M. K (1971); "Numerical Solution of Differential Equations (2<sup>nd</sup> Edition)", Wiley Eastern Limited, New Delhi.