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Automated street lighting control

S. O. Igbinovia¹, R. O. Osayande², and S. Omodamwen³ ^{1, 2, 3} Department of Electrical and Electronic Engineering, Faculty of Engineering, University of Benin, Benin City, Nigeria.

Abstract

The control of street lights in some of the streets outside the campus and in university of Benin, Ugbowo Campus, Benin City, using Switching control circuit interfaced with a computer to enable effective control of the street light was investigated in this work.

The methodology adopted in this work includes:

> Designing and constructing a dc power supply unit which provides +12Volts and +5Volts to power the transistorized switching logic circuits and the Multiplexers respectively,

> Designing a suitable interface,

> Developing a control program written in visual Basic which is linked to the hardware with the help of the dynamic link library [DLL] program,

> Demonstrating the model work which had twelve 40 Watts connected in three circuits depicting the adjoining streets.

The sequence of address inputs and outputs functions are indicated and generated by the computer program. The switching time and delay time of ON/OFF of the circuits are dependent on weather and not time of the day. To have effective response signal of the weather we used photocells which drive the transistors into saturation and cut – off modes. The automated street lights control capable of handling up 167Amp. Current at 230Volts, and intended to eliminate human inadequancies, worked satisfactorily. The relevance of this scheme is its capability of saving electric energy consumption and reduction in man hour which translates to revenue saving. All these could results in new concept and development in our environment.

Nomenclature

DLL: Dynamic link library, IC: Integrated circuit, KBPs: Kilobytes per seconds LPT: Link port terminal, PID: Proportional integral differential, TDM: Time division Multiplexing, TTL: Transistor-transistor logic, VB: Visual basic

1.0 IntroductionMan over the decades has transformed his primitive nature to highly developed and proven technology. To eliminate the problems associated with inadequacies in man's physical senses and reliability, automated circuits are been introduced into processes to enhance systems overall efficiency. These desired automated circuits reduce stress and energy as it controls itself and are seldom dependent on human intervention in case the need arises. This project was necessitated because from our observation from the offices, most times the switching time goes far into the evenings before the operators' switches on the adjourning street lights behind electrical/electronic engineering department.

¹e-mail: <u>samigbinovia2006@yahoo.com</u>

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Since our interest in this work is automating street lighting in order to switch ON the circuits at appropriate time of the day at dawn i.e once the natural sunlight goes down after sunset, meaning ambient illuminance goes below 60 Lux, and OFF at dawn on sensing the illuminance level to be above 10Lux [1] to save electric energy consumption, which translates into operating cost savings, the adequately designed automated street lighting control facilitates the following:

- Enhancement of vision during the night,
- Reduces mishap/ accidents, resulting in most cases amputation and lost of life,
- Security consciousness, thus encouraging free movements,
- Encourages commercial activities,
- Wade-off night marauders, burglary and robbery activities,
- Photocell sensor with a defined field of view,
- Facility for selecting time selection and good resolution,
- Saves electric energy consumption and
- Precise timeliness

The non-provision of street lights virtually along our various categories of roads in Nigeria, lack of maintenance and the manual/mode of operation of the existing ones and coupled with the insistence vandalization of the circuit, it becomes very necessary to incorporate automatic control modes in street light circuits and investigate such systems using locally developed codes in visual basic.

In section 2 of this work the operating principles of the work is presented, Section 3 presents the system design, while section 4 illustrates how the streets were modeled to demonstrate the automation. The controlled circuit results are presented in section 5, while section 6 concludes the work.

2.0 **Operating principles**

The operation of the device is based on direct sequence spread spectrum technology [2]. The designed and constructed automated street light controller is interfaced with a computer with controlled sequence of instructions which reduced the stress of moving from one location to another location of switching to turn ON/OFF the street lights. The control circuit is made up of three stages as shown in Figure 2.1.

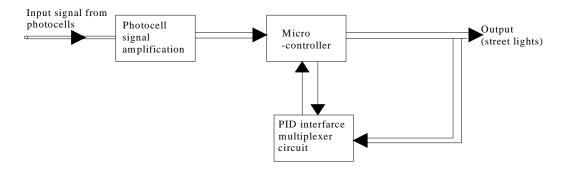


Figure 2.1: Multivariable control system for the street light

The street light circuits are burden in sections, the photocells with the help of the computer sends control signals to the circuits depending on the address in binary codes that has been sent by the computer to the control section via the parallel port. The operation is controlled by sequence of instructions written in visual basic. The signals from the photocells are amplified, converted and fed into the controller. The interface is made possible via the use of DB25 parallel port. The 9 pins used in the parallel port were grouped into input and output pins in order to eliminate off-set voltages between computer parallel port and designed circuits. The parallel port which transmits 8 bits from the A/DC simultaneously has a maximum data rate of 6KBPS, which exceeds our requirement of 1KBPS [3, 4].

The output of the parallel port is TTL compatible, thus no special interfacing. The cost of operating parallel port arrangement is relatively cheap and this out-weights the disadvantage of average cost of using computer.

Operating the transistors in saturation and cut-off modes with minimum power dissipation enables the transistorized relays to make and break the particular street lights circuit. Advancement in electronic elements technology has in a long way improved the resolution, stability and sensitivity of control and computer systems.

The time required for the transistor to switch from the "OFF to ON" and "ON to OFF" stages in miliseconds respectively are [4, 5];

$$t_{on} = t_r + t_d \tag{2.1}$$

$$t_{off} = t_s + t_f \tag{2.2}$$

where

 t_r = rise time from 10% to 90% of final value

 t_d = delay time between changing state of the input

 t_f = storage time

 t_f = fall time from 90% to 10% of initial value

These values are dependent on the speed of response and the collector current response. To actualize the functionality of this circuit, CD 4051 8-channels multiplexer with only 2 address lines to reduce the state of the multiplexer to 4 while others grounded were utilize. Table 1.0 shows the base address for LPTI and Typical computer used in this work. The table enables pins combination, the capacity and type of information's in the bus, the expected I/O data and the variable addresses.

Table 2.1: Base address for LPT1/Typical computer

Register	Pins	LPT1	Function
Data register	[2-9]	378[hex]	Input-output
Status	[10-13, 15]	379 [hex]	Input
Control	[1,14,16,17]	37A [hex]	Output
Ground	[18-25]		Ground

3.0 System design

The design of the street light control system involves the use of computer to analyse the feedback signals from the electronic circuit [hardware] and software (drives, and the main program).

3.1 Design calculations

3.1.1 DC power supply

The essential parameters for the power supply unit and sensory circuit design for the interface are as follow [3, 4, 5, 6].

The step-down transformer transforms the 220 main supply voltages to no-load 15V AC which is rectified to get +12V DC and +5VDC required in the sub- circuits. The transformation ratio is given by the relationship;

$$\frac{V_P}{V_S} = \frac{220}{15} = 14.66:1 \tag{3.1}$$

The power transfer efficiency of the transformer is given by the relation;

$$V_{\rm p} \times I_{\rm p} = V_s \times I_s \times \eta \tag{3.2}$$

where, η = percentage efficiency of the transformer

 $V_{\rm p}$ = primary voltage

 $V_s^{\rm P}$ = secondary voltage

 I_p = primary current

 I_s^{P} = secondary current

The rectified pulsating peak voltage is given by the relation;

$$V_{\rm PDV} = 15 - 2V_{\rm D} = 15 - (2 \times 0.6) = 13.80 \text{V}$$
 (3.3)

where, V_D is the voltage drop across the diode.

The average output voltage from the rectifier circuit is; $V_{OAV} = V_{PDV} \times 0.638$

In this wise IC 7812 and 7805 were used to achieved DC output full-load voltages of +12V and +5V in the circuitry. To calculate and select the capacitor required in filtering the ripples, equation 7 was used.

= 13.8 x 0.638 = 8.80 Volts

Ripple of the output voltage =
$$\frac{V_{RMS}}{V_{DC}} \ge 125\%$$
 (3.5)
= $\frac{15}{12} \times 100 = 125\%$

This implies that 25% regulation was done in filtering the pulsating DC voltage waveform to achieve the pure DC voltage.

3.1.2 Lamp parameters calculation

The current (I) flow across each of the 40Watts bulb is given by;

$$I = \frac{P}{V} = \frac{40}{220} = 0.182 Amps.$$
(3.6)

The allowable voltage drop across the lamp resistor, R_L is;

$$V_{AVD} = IR_{L} = 0.182 \times 40 \Omega = 7.28V$$
The maximum power loss (P₁) in the lamps is;
(3.7)

 $P_L = I^2 R_L = (0.182)^2 \times 40 = 1.33$ watts (3.8)

Twelve (12) Lamps were used to represent the three adjoining streets in the model. Thus the full load current allowed in the circuit is 2.18Amps.

3.1.3 Calculation for the transistorised relay switching parameters

The base current for transistor Q24, is obtained from;

$$I_{\rm B} = \frac{I_C}{\beta} = \frac{1x10^{-3}}{60} = 16.67\,\mu A \tag{3.9}$$

where, I_C = collector current, Amps

 β = forward gain of the device, for this case (= 60)

Applying kirchoff's current law, the collector limiting resistance is given by;

$$R_{BB} = R_{29} + R_{36}$$
(3.10)
$$= \frac{V_{CC} - 0.7}{I_{R}} = \frac{5 - 0.7}{16.67 \times 10^{-6}} = 258.00 K\Omega$$

The base Resistor, R_B of transistor Q12 is $R_{36} = R_X = 43K \Omega$, which is chosen as R_C . Therefore the collector response current for transistor Q25 is;

$$I_{C} = \frac{V_{CC}}{R_C} = \frac{5}{43} = 116\mu A$$
(3.11)

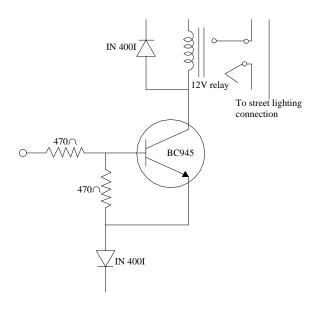
The base limiting resistor for transistor Q25 is;

$$=\frac{V_B - 0.7}{I_B}.$$
(3.12)

$$=\frac{V_B - 0.7}{I_{C_2} / \beta} = \frac{7.23 - 0.7}{\frac{116 \times 10^{-6}}{60}} = \frac{7.16}{1.94 \times 10^{-6}} = 3.36 M\Omega$$

3.2 The controller circuits

This entails the design of the controller and the multiplexer circuits components shown in Figures 3.1 and 3.2 for effective switching of the circuits [3, 4, 5] respectively.



The multiple?

Figure 3.1: Control circuit

e street lights along each street. A binary address is used to select which of the input signals appears at the output [3]. The outputs of the multiplexers are the status signal of the bulbs at different sections of the street to the computer as depicted in Figure 3.2. The technique adopted in this work is called time division multiplexing (TDM) [3].

The multiplex operation is based on the formula;

 $2^{n} = N$

(3.13)

where, n = number of inputs or addresses, which is two in this case

N = number of outputs or states

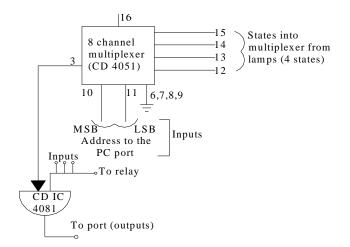


Figure 3.2: Multiplexer input and output connection for the different streets

3.3 Interface stage

The interface entails the contact point between the system and hardware. A printer port also known as the parallel port (DB25 connector) consisting of 25 pins was used. These pins were classified into four major signals namely: Data, status, control and ground lines [3, 4]. The interface connection for the hardware is as shown in Figure 3.3. When the pins of the data line connected to the relay that puts ON/OFF the street lights are high (i.e. when the program send a logic 1 to these pins), the relays

actuates to put ON the lights, while if the pins signals are low (i.e. when the program sends a logic 0) the relays, de-actuates and put OFF the lights.

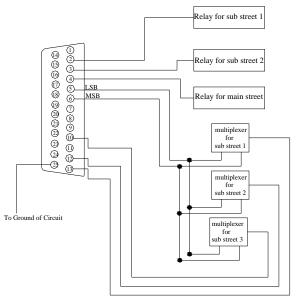


Figure 3.3: Interface connection of the hardware

3.4 Software drivers

To design the software that reads the state of the pins and act promptly, it was divided into DLL and VB programs [7, 8].

3.4.1 Dynamic link library (DLL) program

This (DLL) program is needed by the visual Basic (VB) program to communicate with the port (i.e a step before compiling), using codes like (Delphi, Borland C++ or Microsoft visual C++) during run-

time (dynamically). In writing this program that works with all versions of windows operating system, the following sequences were followed:

- (i) Write VC ++ code that uses Read/Write functions
- (ii) Compile it into a DLL (instead of an executable file)
- (iii) Call your functions from VB

3.4.2 Visual basic (VB) program development

The program (VB) considered manual setting of the street lights, setting general ON/OFF times and enabled feed backs. The slide below the timers is used to increase or decrease the delay time in controlling the ON/OFF switching time of the street lights.

Despite its appropriate speed visual basic programming language was used due to the following reasons:

(i) Not for the ease of learning but support for rapid application development (RAD)

(ii) It takes no lines of sources codes to create an application frame, but simply drags, design form and manipulates (i.e. easy of upgrading)

(iii) It is interpreted rather than compiled with VB. Conversion from the intermediary code to machine code is done with what is called visual machine.

(iv) It is an event driven program

(iv) It has support for abject oriented programming

(vi) The codes are in modules and this reduces the changes of bugs.

Though the high level language has the above advantages, the following disadvantages manifest in its running:

(i) Lack of access port

(ii) Interpreted, hence slower than C/C++

The lack of access port in this work was overcome using infrastructure which is supported by VB.

4.0 Modeling of the street lights

To demonstrate the functionality of the designed automatic control system, the road linking social sciences from faculty of engineering and some of the adjoining roads were mapped on a board using twelve 40Watts bulbs as a prototype.

5.0 Results

The developed code in this work is as contained in appendix 1. The display default provides an interface for the user to send information to the circuits and also receive feedback signals from the circuits. The developed program ran perfectly well in the auto – stage. When the controlled circuit was disabled for manual operation of the street lights the scheme also worked perfectly.

6.0 Conclusion

The implementation of the conceived scheme: Design and Construction of an automated model for streets lighting control was feasible. Using a computer interface and with the help of a visual basic programming, it was easy to write windows 32-bit applications which communicate with the hardware link DLL through the parallel port of the computer. This has been able to solve the problem arising from man's inefficient attitude in performing their imposed duties of street lights control. The cost of schemes of this nature depends relatively on the circuit complexity.

The automated control system also allows manual operation of the switching arrangement of the street light. Though it is a costlier scheme to operate, its operating efficiency and energy saving cost is worth implement ting in controlling street lights. The most facilitating aspect of this device is that it's intelligent enough to sense the Lux level depending on the weather condition inrespective of the mains power and activate the switches.

Appendix 1: Visual Basic (VB) Code Listing for the Automated street lighting control

The code for the automated street lighting control using VB programming language is show in this section. The code was developed by: S. O.Igbinovia, R. O. Osayande, and S.Omodamwen, Department of Electronics and Electectrical Engineering, Faculty of Engineering, University of Benin, Benin city, Nigeria.

Option Explicit

'Send a value to a specified port Private Declare Sub PortOut Lib "IO.DLL" (ByVal Port As Integer, ByVal Data As Byte) ' Returns a value from specific ports. Private Declare Function PortIn Lib "IO.DLL" (ByVal Port As Integer) As Byte 'Delay for in Miliseconds Private Declare Sub Sleep Lib "kernel32" (ByVal dwMilliseconds As Long) Public delayTime As Single Private Sub cmdExit_Click() End End Sub Private Sub Form_Load() PortOut 888, 0 End Sub Private Sub iSliderX1_OnPositionChange() iSliderX1.ToolTipText = iSliderX1.Position *delayTime* = *iSliderX1.Position* End Sub *Private Sub iSliderX1 OnPositionChangeFinished()* iSliderX1.ToolTipText = iSliderX1.Position End Sub *Private Sub iSwitchLeverX1_OnChange()* Dim i As Integer

```
If Not iSwitchLeverX1.Active Then
       For i = 0 To 3
                 ledSub1(i).Active = False
       Next i
        PortOut 888, PortIn(888) And 253
Else
       For i = 0 To 3
                 ledSub1(i).Active = True
       Next i
                 PortOut 888, PortIn(888) Or 2
       End If
End Sub
Private Sub iSwitchLeverX2 OnChange()
Dim i As Integer
       If Not iSwitchLeverX2.Active Then
       For i = 0 To 3
                 ledSub2(i).Active = False
       Next i
       PortOut 888, PortIn(888) And 251
       Else
                 For i = 0 To 3
                 ledSub2(i).Active = True
       Next i
       PortOut 888, PortIn(888) Or 4
       End If
End Sub
Private Sub iSwitchLeverX3_OnChange()
Dim i As Integer
       If Not iSwitchLeverX3.Active Then
```

```
For i = 0 To 3
                 ledMain(i).Active = False
       Next i
                 PortOut 888, PortIn(888) And 254
       Else
                 For i = 0 To 3
       ledMain(i).Active = True
       Next i
       PortOut 888, PortIn(888) Or 1
       End If
End Sub
Private Sub OffTime_OnDblClick()
       Dim value As Integer
       value = Int(Val(InputBox("Enter the hour part of the Off Time", "ON TIME", "6")))
       OffTime.value = value
       Switch2.value = Int(OffTime.value) * 60 + (OffTime.value - Int(OffTime.value))
End Sub
Private Sub OnTime_OnDblClick()
       Dim value As String
       value = Int(Val(InputBox("Enter the hour part of the On Time", "ON TIME", "6")))
       OnTime.value = value
       Switch1.value = Int(OnTime.value) * 60 + (OnTime.value - Int(OnTime.value))
End Sub
Private Sub optSLTime_Click(Index As Integer)
       If optSLTime(0).value Then
                 Frame2.Enabled = True
                 Frame3.Enabled = False
                 Timer3.Enabled = False
Else
                 Frame2.Enabled = False
                 Frame3.Enabled = True
                 Timer3.Enabled = True
       End If
End Sub
Private Sub Switch1_OnValueChange()
       OnTime.value = Int(Switch1.value / 60) + ((Switch1.value Mod 60) / 100)
       If Switch1.value \geq 1440 Then
       OnTime.value = 0
       Switch1.value = 0
       End If
End Sub
Private Sub Switch2_OnValueChange()
       OffTime.value = Int(Switch2.value / 60) + ((Switch2.value Mod 60) / 100)
       If Switch2.value >= 1440 Then
       OffTime.value = 0
                 Switch2.value = 0
       End If
End Sub
Public Function Read(bulb As Integer) As Integer
'Pins 4 and 5 for selecting the Multiplexer
'Pins 13,12,10 for reading from the Multiplexer
       Dim DataPort As Integer, StatusPort As Integer
       DataPort = Val("&H378")
       StatusPort = Val("&H379")
       Select Case bulb
       'Read from first Multiplexer through pin 13 (for SUB-1)
```

```
Case 1
```

PortOut DataPort, PortIn(DataPort) And 231 'send 00 to Mul

	PortIn(StatusPort) And 16
Case 2	PortOut DataPort, PortIn(DataPort) Or 8 'send 01 to Mul
	Read = PortIn(StatusPort) And 16
Case 3	
	PortOut DataPort, PortIn(DataPort) And 231 'Send 00 to Mul PortOut DataPort, PortIn(DataPort) Or 16 'send 10 to Mul
	Read = PortIn(StatusPort) And 16
Case 4	
	PortOut DataPort, PortIn(DataPort) Or 24 'send 11 to Mul
	Read = PortIn(StatusPort) And 16 'Read from second Multiplexer through pin 12 (for SUB-2)
Case 5	Read from second multiplexer intough pin 12 (for 50D-2)
	PortOut DataPort, PortIn(DataPort) And 231 'send 00 to Mul
<i>a</i> (Read = PortIn(StatusPort) And 32
Case 6	PortOut DataPort, PortIn(DataPort) Or 8 'send 01 to Mul
	Read = PortIn(StatusPort) And 32
Case 7	
	PortOut DataPort, PortIn(DataPort) And 231 'send 00 to Mul
	PortOut DataPort, PortIn(DataPort) Or 16 'send 10 to Mul
Case 8	Read = PortIn(StatusPort) And 32
euse o	PortOut DataPort, PortIn(DataPort) Or 24 'send 11 to Mul
	Read = PortIn(StatusPort) And 32
Care 0	'Read from third Multiplexer through pin 10 (for MAIN)
Case 9	PortOut DataPort, PortIn(DataPort) And 231 'send 00 to Mul
Case 10	Tonou Duuron, Tonm(Duuron) nna 251 sena 66 io ina
	PortOut DataPort, PortIn(DataPort) Or 8 'send 01 to Mul
<i>c</i> 11	Read = PortIn(StatusPort) And 64
Case 11	PortOut DataPort, PortIn(DataPort) And 231 'send 00 to mul
	PortOut DataPort, PortIn(DataPort) Or 16 'send 10 to Mul
	Read = PortIn(StatusPort) And 64
	Case 12 PortOut DataPort, PortIn(DataPort) Or 24 'send 11 to Mul
	Read = PortIn(StatusPort) And 64
	End Select
End Fi	
	Sub Timer1_Timer()
	eedback.value Then chLeverX1.Active Then
1 <i>j</i> 15771	If $Read(1) = 0$ Then
	iLCDMatrixX1.PlaceText "Sub1: B1 is DEAD", 1, 0, vbRed
171	<i>ledSub1(0).Active = False</i>
Else	iLCDMatrixX1.PlaceText "Sub1: B1 is GOOD", 1, 0, vbGreen
	ledSub1(0).Active = True
End If	
If Read	P(2) = 0 Then
	<i>iLCDMatrixX1.PlaceText "Sub1: B2 is DEAD", 1, 1, vbRed</i> <i>ledSub1(1).Active = False</i>
Else	$teusuo_1(1)$. Active – Γ uise
2.50	iLCDMatrixX1.PlaceText "Sub1: B2 is GOOD", 1, 1, vbGreen
	ledSub1(1).Active = True
If Read	(3) = 0 Then iLCDMatrixY1 PlaceText "Sub1: P3 is DEAD" 1.2 wbPad
	iLCDMatrixX1.PlaceText "Sub1: B3 is DEAD", 1, 2, vbRed

```
ledSub1(2).Active = False
Else
       iLCDMatrixX1.PlaceText "Sub1: B3 is GOOD", 1, 2, vbGreen
       ledSub1(2).Active = True
End If
If Read(4) = 0 Then
       iLCDMatrixX1.PlaceText "Sub1: B4 is DEAD", 1, 3, vbRed
       ledSub1(3).Active = False
Else
       iLCDMatrixX1.PlaceText "Sub1: B4 is GOOD", 1, 3, vbGreen
       ledSub1(3).Active = True
End If
Else
       iLCDMatrixX1.PlaceText " ", 1, 0, vbYellow
iLCDMatrixX1.PlaceText " ", 1, 1, vbYellow
iLCDMatrixX1.PlaceText " ", 1, 2, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 3, vbYellow
End If
If iSwitchLeverX2.Active Then
        If Read(5) = 0 Then
       iLCDMatrixX1.PlaceText "Sub2: B1 is DEAD", 1, 4, vbRed
       ledSub2(0).Active = False
Else
       iLCDMatrixX1.PlaceText "Sub2: B1 is GOOD", 1, 4, vbGreen
       ledSub2(0).Active = True
End If
If Read(6) = 0 Then
       iLCDMatrixX1.PlaceText "Sub2: B2 is DEAD", 1, 5, vbRed
       ledSub2(1).Active = False
       iLCDMatrixX1.PlaceText "Sub2: B2 is GOOD", 1, 5, vbGreen
       ledSub2(1).Active = True
Else
End If
If Read(7) = 0 Then
       iLCDMatrixX1.PlaceText "Sub2: B3 is DEAD", 1, 6, vbRed
       ledSub2(2).Active = False
       Else
       iLCDMatrixX1.PlaceText "Sub2: B3 is GOOD", 1, 6, vbGreen
       ledSub2(2).Active = True
End If
If Read(8) = 0 Then
       iLCDMatrixX1.PlaceText "Sub2: B4 is DEAD", 1, 7, vbRed
        ledSub2(3).Active = False
Else
       iLCDMatrixX1.PlaceText "Sub2: B4 is GOOD", 1, 7, vbGreen
       ledSub2(3).Active = True
       End If
Else
       iLCDMatrixX1.PlaceText " ", 1, 4, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 5, vbYellow
       iLCDMatrixX1.PlaceText ", 1, 6, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 7, vbYellow
End If
If iSwitchLeverX3.Active Then
       If Read(9) = 0 Then
                 iLCDMatrixX1.PlaceText "Main: B1 is DEAD", 1, 8, vbRed
                 ledMain(0).Active = False
       Else
         iLCDMatrixX1.PlaceText "Main: B1 is GOOD", 1, 8, vbGreen
```

```
ledMain(0).Active = True
       End If
       If Read(10) = 0 Then
                iLCDMatrixX1.PlaceText "Main: B2 is DEAD", 1, 9, vbRed
                ledMain(1).Active = False
       Else
                iLCDMatrixX1.PlaceText "Main: B2 is GOOD", 1, 9, vbGreen
                ledMain(1).Active = True
       End If
       If Read(11) = 0 Then
       iLCDMatrixX1.PlaceText "Main: B3 is DEAD", 1, 10, vbRed
       ledMain(2).Active = False
       Else
                iLCDMatrixX1.PlaceText "Main: B3 is GOOD", 1, 10, vbGreen
         ledMain(2).Active = True
         End If
         If Read(12) = 0 Then
         iLCDMatrixX1.PlaceText "Main: B4 is DEAD", 1, 11, vbRed
         ledMain(3).Active = False
         Else
         iLCDMatrixX1.PlaceText "Main: B4 is GOOD", 1, 11, vbGreen
                ledMain(3).Active = True
       End If
Else
       iLCDMatrixX1.PlaceText " ", 1, 8, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 9, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 10, vbYellow
       iLCDMatrixX1.PlaceText " ", 1, 11, vbYellow
End If
Else
       Dim i As Integer
       For i = 0 To 11
                iLCDMatrixX1.PlaceText " ", 1, i, vbYellow
       Next i
End If
End Sub
Private Sub Timer2_Timer()
Static c As Integer
                c = c + 1
       If c = 9 Then
         c = 0
                Unload Me
                Me.Show
       End If
End Sub
Private Sub Timer3_Timer()
Dim i As Long
       Timer1.Enabled = False
       Timer2.Enabled = False
       'Check for the on times and put on the bulbs as needed
       If Int(Switch2.value / 60) = Hour(Time) And Int(Switch2.value Mod 60) = Minute(Time) Then
       Timer3.Enabled = False
       iSwitchLeverX1.Active = False
       For i = 1 To 600
                Sleep (CInt(iSliderX1.Position))
       DoEvents
       Next i
```

```
iSwitchLeverX2.Active = False
                  For i = 1 To 600
         Sleep (CInt(iSliderX1.Position))
                  DoEvents
         Next i
         iSwitchLeverX3.Active = False
ElseIf Int(Switch1.value / 60) = Hour(Time) And Int(Switch1.value Mod 60) = Minute(Time) Then
         Timer3.Enabled = False
         iSwitchLeverX1.Active = True
         For i = 1 To 600
         Sleep (CInt(iSliderX1.Position))
         DoEvents
         Next i
         iSwitchLeverX2.Active = True
         For i = 1 To 600
         Sleep (CInt(iSliderX1.Position))
         DoEvents
Next i
         iSwitchLeverX3.Active = True
End If
         Timer1.Enabled = True
         Timer2.Enabled = True
         Timer3.Enabled = True
```

```
End Sub
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References

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