

On the Lie Algebra of an Algebraic Group

Henry O. Omokaro

Department of Mathematics, University of Benin, Benin City, Nigeria.

Abstract

Given an algebraic group G one can associate with it a Lie Algebra \mathfrak{g} . In this paper we discuss how much the structure of \mathfrak{g} reflects the structure of G . Other issues concerning \mathfrak{g} are also looked at.

pp 23 - 26

1.0 Introduction

1.1 Definition

A set G which satisfies the following conditions is called an *Algebraic group*.

- (i) G is a group
- (ii) G is a topological space with respect to the Zariski topology
- (iii) The function $G \times G \rightarrow G$ of $(x, y) \rightarrow xy$ is a morphism of varieties.
- (iv) The function $G \rightarrow G$ of $x \rightarrow x^{-1}$ is a morphism of varieties.

Examples of algebraic groups can be found in [5]. It is important to note that an algebraic group is not a topological group except in dimension zero. In a topological group G , $G \times G$ has the product topology whereas in an algebraic group G , $G \times G$ has the Zariski topology.

Studies have shown that whenever we have an algebraic group G we can identify with G a Lie algebra \mathfrak{g} [3]. The manner in which \mathfrak{g} is constructed from G is a functorial one. In the next section we discuss some of the effects of G on the structure of its Lie algebra \mathfrak{g} .

2.0 The Structure of Lie Algebra

Given an algebraic group G one can show that the set of all derivations $\text{Der } A$ of A is an algebra where $A = K[G]$. One can also show that the bracket of two derivations of A is also a derivation of A . So, it follows that the algebra of derivations of A is in fact a Lie algebra.

When G acts on A via left translation we obtain

$$\lambda_x : (\lambda_x f)(y) = f(x^{-1}y).$$

Similarly, when it acts on A via right translation we obtain

$$\rho_x : (\rho_x f)(y) = f(yx).$$

Now consider the following subspace of $\text{Der } A$.

$$\{\delta \in \text{Der } A : \delta \lambda_x = \lambda_x \delta \quad \forall x \in G\}.$$

This is called the space of *left invariant derivations* of A .

Now the bracket of two derivations of A , which commutes with λ_x , must also commute with x , so that the left invariant derivations of A is a Lie algebra. This Lie algebra we will write as $L(G)$. We shall call it the *Lie Algebra* of G .

Several natural questions arise when we take a look at $L(G)$ and G as a way of comparison. Some of such questions are:

- (i) is $L(G)$ finite dimensional?
- (ii) if $L(G)$ is finite dimensional what is its dimension?
- (iii) if $\phi : G \rightarrow G^1$ is a morphism of algebraic groups, how does this behave as a carry over to the Lie algebras $L(G)$, $L(G^1)$ of the algebraic groups G and G^1 respectively?

(iv) How does the structure of $L(G)$ reflect the group structure of G ?

(v) If H is a closed subgroup of G how is $L(H)$ related to $L(G)$?

Let $T(G)_e$ represent the tangent space of G at the identity. Usually $T(G)_e$ is identified with $T(G^0)_e$, where G^0 is the identity component of G . It has the structure of a vector space over K ; its dimension is equal to the dimension of G because e is a simple point. We write

$$T(G)_e \text{ as } \mathfrak{g}.$$

Let $\phi: G \rightarrow G^1$ be a morphism which sends e to e . An example of this is a morphism of algebraic groups. ϕ induces the following linear map:

$$d\phi_e: \mathfrak{g} \rightarrow \mathfrak{g}^1.$$

This map $d\phi_e$, differential of ϕ , has the following functorial properties.

(i) $d(I_G) = I_{\mathfrak{g}}$ where I_G and $I_{\mathfrak{g}}$ are the identity elements of G and \mathfrak{g} respectively.

(ii) $d(\Psi_0\phi)_e = d\psi_{e0}d\phi_e$

We can describe $T(G)_e$ algebraically as the space of point derivations from the local ring at e into K . But we know that such derivations are already uniquely determined by their effect on $A = K[G]$ as a subring. Naturally, this gives one the impression that one can link up \mathfrak{g} from $L[G]$. This is done by evaluating functions at e .

The following result establishes an isomorphism between the Lie algebra between the Lie algebra $L(G)$ of an algebraic group G and the tangent space $T[G]_e = \mathfrak{g}$ of G at the identity element e . In addition, if $\phi: G \rightarrow G^1$ is a morphism of algebraic groups it shows how the induced space map from \mathfrak{g} the tangent space of G to \mathfrak{g}^1 the tangent space of G^1 behaves.

3.0 Theorem [3]

Let G be an algebraic group $\mathfrak{g} = T(G)_e$, $L(G)$ as above. Then

$$\theta: L(G)_e \rightarrow \mathfrak{g}$$

such that

$$(\theta\delta)(f) = (\delta f)(e) \text{ for all } \delta \text{ in } L(G),$$

f in A is a vector space isomorphism. In case $\phi: G \rightarrow G^1$ is a morphism of algebraic group $d\phi_e: \mathfrak{g} \rightarrow \mathfrak{g}^1$ is a homomorphism of Lie algebra ($\mathfrak{g}, \mathfrak{g}^1$ being given the bracket product of $L(G), L(G^1)$ respectively)

Since there exists an isomorphism between $T(G)_e$ and $L(G)$ from the theorem it follows that we can as well study $T(G)_e$ in place of $L(G)$ and obtain the desired results. In particular, since the dimension of G is equal to the dimension of $T(G)_e$, it follows that the dimension of G is equal to the dimension of $L(G)$. Therefore, if G is finite dimensional, then \mathfrak{g} is also finite dimension and the first two questions above have been answered.

It is important to know that the fact that every $\delta \in L(G)$ is invariant means that the tangent vector at e determined by δ is assigned through left translations to the various tangent vectors at other points e determined by δ . As a result, δ is determined by the tangent vector $f \rightarrow (\delta f)(e)$; and also any tangent vector at e should also give rise to such left invariant derivation. We illustrate this by looking at the following example.

Example

Let x be fixed element of an algebraic group G . Consider the function:

$$\text{Int } x: G \rightarrow G \text{ such that } \text{Int } x = xyx^{-1} \quad \forall y \in G.$$

One can show that $\text{Int } x$ is a morphism of G [5]. Its differential $d(\text{Int } x)$ is denoted by Ad_x .

Now Ad_x is an automorphism of the algebra \mathfrak{g} . To show it is invertible, consider

$$(Adx)(Adx^{-1}) = d(\text{Int } x)_0 d(\text{Int } x^{-1}) = d(\text{Int } xx^{-1}) = d(\text{Int } e) = 1g$$

where $1g$ is the identity element of the Lie algebra g associated with G .

Consider the function

$$Ad : G \rightarrow \text{Aut}(g) \rightarrow GL(g)$$

such that $Ad(x) = Adx$. Let $x, y \in G$. Consider

$$Ad(xy) = (Adx)(Ady) = Adxy.$$

Therefore Ad is a homomorphism of abstract groups. In other words, it is a representation of G .

Next, let us look at the effect of Adx on g through the map $\theta : L(G)_e \rightarrow g$ defined earlier. Now suppose $Adx(\delta) = \delta^1$ by definition. $(\delta^1 f)(e) = \delta(\phi^* f)(e) \forall f \in K[G]$ where $\phi = \text{int } x$. This applies in particular to functions of the form $\rho_x f$. But

$$\phi^*(\rho_x f)(y) = (\rho_x f)(xyx^{-1}) = f(xy) = (\lambda_{x^{-1}} f)y,$$

that is $\phi^*(\rho_x f) = \lambda_{x^{-1}} f$.

Now $(\delta^1 \rho_x f)(e) = \delta(\lambda_{x^{-1}} f)(e) = \lambda_{x^{-1}}(\delta f)(e) = (\delta f)(x)$, δ is left invariant $(\delta f)(e)$. We conclude that $\delta^1 = \rho_x \delta \rho_x^{-1}$. Therefore $Adx(\delta) = \rho_x \delta \rho_x^{-1}$. So the effect of Adx on each derivation δ is that it conjugates it with ρ_x for each $x \in G$.

4.0 Definition

Let G be an algebraic group and g its Lie algebra. The homomorphism $Ad : G \rightarrow GL(g)$ is called the *adjoint representation* of G .

Let us consider a closed subgroup H of an algebraic group G . The induced map $i : H \rightarrow G$ is an isomorphism of H onto a closed subgroup of G . i therefore induces a map $i^* : K[G] \rightarrow K[H]$. But $K[H]$ is isomorphic to $K[G]/I$, where I is the ideal vanishing on H , by the first isomorphism theorem. It follows that d_{ie} identifies $T(H)_e$ with the subspace of $T(G)_e$ consisting of those x for which $x(I) = 0$. But i is also a morphism of algebraic groups implies $di : h \rightarrow g$ is a Lie algebra homomorphism. This allows us to view h as a Lie sub algebra of g .

In [1] there is a characterization for the closed subgroups H of an algebraic group G . From the right convolution the following is a similar characterisation of h in g for any closed subgroup H of G .

4.1 Theorem [1]

Let H be a closed subgroup of G : I the ideal of $K[G]$ vanishing on H . Then $h = \{x \in g : I^* x \subset I\}$.

5.0 Conclusion

It is observed that the passage from an algebraic group G to its associated Lie algebra g is a functorial one which is such that most of the results true for G also have their corresponding results in g . One of these is that if G is finite dimensional then its Lie algebra g is also finite dimensional. If H is a closed subgroup of G , through the morphical action of G on itself we have a characterization of such H . Correspondingly, through right convolution in g , we also have a characterization of h .

It is also observed that if $\phi : G \rightarrow G^1$ is a morphism of algebraic groups then its differential $d\phi_e : g \rightarrow g'$ the identity element is also a Lie algebra homomorphism from g to g' .

References

- [1] Borel, A (1985) Linear Algebraic Groups, New York: Springer Verlag

- [2] Banachoff, T., Werner J. (1980) Linear Algebra through Geometry.
- [3] Humphreys, J. E. (1975) Linear Algebraic groups. New York: Springer Verlag
- [4] Serre, J. P. (1975) Algebraic Groups and Class field. New York: Springer Verlag.
- [5] Omokaro, H. O. (1996) Action of Algebraic Groups I.C.T.P., Diploma Programme Thesis, Trieste, Italy.
- [6] Waterhouse, W. C. (1979) Introduction to Affine Group Schemes. New York: Springer Verlag.