In honour of Prof. Ekhaguere at 70 Two factors exponential type estimator for population mean under single phase sampling scheme

O. O. Ishaq^{a*} and **A. Audu**^b

^aDepartment of Statistics, Kano University of Science and Technology, Wudil, Nigeria; ^bDepartment of Mathematics, Usmanu Danfodiyo University, Sokoto, Nigeria

Abstract. In this article, we have proposed two factors exponential type estimator for finite population mean under single phase sampling scheme. The bias and meansquare error (MSE) of the proposed estimator are obtained to the first degree of approximation in section 3. The efficiency of the proposed estimator over sample mean, ratio, product, Bahl and Tuteja [1], Singh and Espejo [3], Solankiet. al. [4] and Khan et. al. [2] estimators had been demonstrated in section 4. We carry out anumerical application showing that the proposed estimator outperforms the traditional estimators using different data sets.

Keywords: bias, efficiency, mean square error, parameters, precision.

1. Introduction

The uses of auxiliary information help in reducing the variability in the estimation of population parameters and thereby increase the precision of the estimators. Let us consider a finite population $U = U_1, U_{,2} \dots U_N$ of size N units and the value of the variables on the i^{th} unit U_i , $i = 1, 2, \dots, N$, be (y_i, x_i) . Let $\bar{Y} = \frac{1}{N} \sum_{i=1}^{N} y_i$ and $\bar{X} = \frac{1}{N} \sum_{i=1}^{N} x_i$ be the population means of the study variable y and the auxiliary variable x, respectively.

The coefficients of variation of these variables are denoted by $C_x^2 = S_x^2/\bar{X}^2$ and $C_y^2 = S_y^2/\bar{Y}^2$ respectively. Further let μ_{20} or S_y^2 and μ_{02} or S_x^2 are corresponding variances. Also, ρ_{xy} will represent population correlation coefficients between X and Y respectively.

For estimating the population mean, a simple random sample of size n is drawn without replacement from the population U. Then the sample mean, classical ratio and product estimators are respectively defined by

$$\hat{\bar{y}} = \bar{y}, \quad \hat{\bar{y}}_R = \bar{y}\frac{\bar{X}}{\bar{x}} \quad if \ \bar{x} \neq 0 an \hat{dy}_P = \bar{y}\frac{\bar{x}}{\bar{X}}$$
(1)

Bahl and Tuteja [1] suggested ratio and product exponential type estimators for population mean as

$$\hat{\bar{y}}_{\rm Re} = \bar{y} \exp\left(\frac{\bar{X} - \bar{x}}{\bar{X} + \bar{x}}\right) \tag{2}$$

$$\hat{\bar{y}}_{Pe} = \bar{y} \exp\left(\frac{\bar{x} - \bar{X}}{\bar{x} + \bar{X}}\right) \tag{3}$$

^{*}Corresponding author. Email: babington4u@gmail.com

For estimating the population mean of the study variable \bar{Y} , Singh and Espejo [3] considered an estimator of the ratio-product type given by

$$\hat{\bar{y}}_{RP} = \bar{y} \left(k \frac{\bar{X}}{\bar{x}} + (1-k) \frac{\bar{x}}{\bar{X}} \right)$$
(4)

Solankiet. al. [4] suggested a class of ratio type estimators for population mean \bar{Y} as

$$\hat{y}_{RHA}^{g} = \bar{y} \left(2 - \left(\frac{\bar{x}}{\bar{X}}\right)^{\alpha} \exp\left(\frac{\delta\left(\bar{x} - \bar{X}\right)}{\bar{x} + \bar{X}}\right) \right)$$
(5)

Khan et. al. [2] proposed exponential ratio and product type estimators for population mean as

$$\hat{y}_{1\left(\sqrt{j}\right)} = \bar{y} \exp\left(\frac{\sqrt{\bar{X}} - \sqrt{\bar{x}}}{\sqrt{\bar{X}} + \sqrt{\bar{x}}}\right) \tag{6}$$

$$\hat{\bar{y}}_{2\left(\sqrt{j}\right)} = \bar{y} \exp\left(\frac{\sqrt{\bar{x}} - \sqrt{\bar{X}}}{\sqrt{\bar{x}} + \sqrt{\bar{X}}}\right) \tag{7}$$

To the second order approximation, the mean square errors of the estimators \hat{y}_R , \hat{y}_P , \hat{y}_{Re} , \hat{y}_{Pe} , \hat{y}_{RP} , \hat{y}_{RHA} , $\hat{y}_{\sqrt{1}}$, and $\hat{y}_{\sqrt{2}}$ respectively are given as

$$\operatorname{var}\left(\hat{Y}\right) = \frac{1-f}{n}S_y^2\tag{8}$$

$$MSE\left(\hat{y}_{R}\right) \simeq \frac{1-f}{n} \left(S_{y}^{2} + R^{2}S_{x}^{2} - 2RS_{xy}\right)$$
(9)

$$MSE\left(\hat{\bar{y}}_{P}\right) \simeq \frac{1-f}{n} \left(S_{y}^{2} + R^{2}S_{x}^{2} + 2RS_{xy}\right)$$
(10)

$$MSE\left(\hat{y}_{\rm Re}\right) \simeq \frac{1-f}{n} \left(S_y^2 + \frac{R^2}{4}S_x^2\left(1-4k\right)\right)$$
 (11)

$$MSE\left(\hat{y}_{Pe}\right) \simeq \frac{1-f}{n} \left(S_y^2 + \frac{R^2}{4}S_x^2\left(1+4k\right)\right)$$
(12)

$$MSE\left(\hat{y}_{RHA}^{1}\right) \simeq \frac{1-f}{n} \left(S_{y}^{2} + \frac{3R^{2}}{4}S_{x}^{2}\left(3-4k\right)\right)$$
(13)

$$MSE\left(\hat{y}_{\sqrt{1}}\right) \simeq \frac{1-f}{n} \left(S_y^2 + \frac{R^2}{16}S_x^2 - \frac{R}{2}S_{xy}\right)$$
(14)

$$MSE\left(\hat{\bar{y}}_{\sqrt{2}}\right) \simeq \frac{1-f}{n} \left(S_y^2 + \frac{R^2}{16}S_x^2 + \frac{R}{2}S_{xy}\right)$$
(15)

Where $k = \frac{\rho \sqrt{\mu_{20}}}{R \sqrt{\mu_{02}}}$ and $R = \frac{\bar{Y}}{\bar{X}}$

2. Proposed estimator

After examining the related estimators in the studies mentioned in Section 1, for estimating the population mean of the main variable under study and motivated by Singh and Shukla [3] estimator of population mean, we proposed the following two factors exponential type estimator

$$\hat{\bar{y}}_{f} = \bar{y} \exp\left(\frac{(d-1)\left(\bar{x}-\bar{X}\right) + (d-2)\left(\bar{X}-\bar{x}\right)}{(d-1)\left(\bar{x}+\bar{X}\right) + (d-2)\left(\bar{X}+\bar{x}\right)}\right)$$
(16)

where $0 < d < \infty$. If d = 1, $\hat{y}_f = \hat{y}_{\text{Re}}$ in eqn(2) and if d = 2, $\hat{y}_f = \hat{y}_{Pe}$ in eqn(3). Our main goal in this paper is to determine the value of d such that the bias and/or the mean square error (MSE) of \hat{y}_f is minimal.

3. Bias and Mean Square Error (MSE) of $\hat{\bar{y}}_f$

To obtain the bias and MSE of \hat{y}_f , we write $e_0 = (\bar{y} - \bar{Y})/\bar{Y}$ and $e_1 = (\bar{x} - \bar{X})/\bar{X}$. So that $\bar{y} = \bar{Y}(1 + e_0)$ and $\bar{x} = \bar{X}(1 + e_1)$ where $|e_0| < 1$ $|e_1| < 1$ are error terms. Hence $E(e_0) = E(e_1) = 0$, $E(e_0) = \frac{1-f}{n}C_y^2$, $E(e_1) = \frac{1-f}{n}C_x^2$, $E(e_0e_1) = \frac{1-f}{n}\rho C_y C_x$ and $f = \frac{n}{N}$

$$\hat{\bar{y}}_f = \bar{Y} \left(1 + e_0 \right) \exp\left(\frac{(B - A) e_1}{(B + A) \left(2 + e_1 \right)} \right)$$
(17)

Where A = d - 1 and B = d - 2. Let $\theta_1 = A + B$, $\theta_2 = B - A$ and $\theta = \frac{\theta_2}{\theta_1}$, then, equation (17) can be written as

$$\hat{\bar{y}}_f = \bar{Y} \left(1 + e_0 \right) \exp\left(\frac{\theta}{2} e_1 \left(1 + \frac{e_1}{2} \right)^{-1} \right)$$
(18)

Expressing $\hat{\bar{y}}_f$ in terms of es to second degree terms of order n^{-1} , we have

$$\hat{\bar{y}}_f - \bar{Y} = \bar{Y} \left(e_0 + \frac{\theta}{2} e_1 - \frac{\theta}{4} e_1^2 + \frac{\theta^2}{8} e_1^2 + \frac{\theta}{2} e_0 e_1 \right)$$
(19)

Taking the expectation of equation (19), we obtain the bias of the proposed estimator as

$$Bias\left(\hat{\bar{y}}_{f}\right) \simeq \bar{Y}\frac{1-f}{n}\left(\frac{\theta}{4}C_{x}^{2}\left(\frac{\theta}{2}-1\right)+\frac{\theta}{2}\rho C_{y}C_{x}\right)$$
(20)

Also, taking square and expectation of equation (19), we obtain the MSE of the proposed estimator up first order approximation as

$$MSE\left(\hat{\bar{y}}_{f}\right) \simeq \bar{Y}^{2} \frac{1-f}{n} \left(C_{y}^{2} + \frac{\theta^{2}}{4}C_{x}^{2} + \theta\rho C_{y}C_{x}\right)$$
(21)

The minimum MSE of the proposed estimator can be obtained by differentiate the equation (21) partially with respect to θ and equate to zero to obtain the optimum value of θ , say θ_{opt} .

$$\frac{\partial MSE\left(\hat{\bar{y}}_{f}\right)}{\partial\theta} = \bar{Y}^{2} \frac{1-f}{n} \left(\frac{\theta}{2}C_{x}^{2} + \rho C_{y}C_{x}\right)$$
(22)

Equate equation (22) to zero; we obtain the optimum value of θ as

$$\theta_{opt} = \frac{-2\rho C_y}{C_x} \tag{23}$$

Substituting the result of equation (23) into equation (21), the minimum MSE of \hat{y}_f is given as

$$MSE\left(\hat{\bar{y}}_{f}\right)_{\min} = \frac{1-f}{n}S_{y}^{2}\left(1-\rho^{2}\right)$$
(24)

Remark 1 It worth noting that the minimum MSE of \hat{y}_f is the same with that of regression estimator when the slope $\beta_1 = \frac{S_{xy}}{S^2}$

To obtain the optimum value of d, we have that $\theta = -v$, $\Rightarrow \quad \frac{\theta_2}{\theta_1} = \frac{B-A}{B+A} = -v$ where $v = \frac{2\rho C_y}{C_x}$ and therefore

$$\frac{(d-2) - (d-1)}{(d-2) + (d-1)} = -v.$$
(25)

By simplifying equation (25), the optimum value of d is obtain as

$$d = \frac{3}{2} + \frac{C_x}{4\rho C_y} \tag{26}$$

4. Efficiency comparisons

From (24) and (8), we have

$$\operatorname{var}\left(\hat{Y}\right) - MSE\left(\hat{\bar{y}}_{f}\right) = \frac{1-f}{n}\rho^{2}S_{y}^{2} > 0.$$

From (24) and (9), we have

$$MSE\left(\hat{\bar{y}}_{R}\right) - MSE\left(\hat{\bar{y}}_{f}\right) = \frac{1-f}{n}\left(\rho S_{y} - RS_{x}\right)^{2} > 0.$$

From (24) and (10), we have

$$MSE\left(\hat{\bar{y}}_{P}\right) - MSE\left(\hat{\bar{y}}_{f}\right) = \frac{1-f}{n}\left(\rho S_{y} + RS_{x}\right)^{2} > 0.$$

From (24) and (11), we have

$$MSE\left(\hat{y}_{\text{Re}}\right) - MSE\left(\hat{y}_{f}\right) = \frac{1-f}{n}\left(\rho S_{y} - \frac{1}{2}RS_{x}\right)^{2} > 0.$$

From (24) and (12), we have

$$MSE\left(\hat{\bar{y}}_{Pe}\right) - MSE\left(\hat{\bar{y}}_{f}\right) = \frac{1-f}{n}\left(\rho S_{y} + \frac{1}{2}RS_{x}\right)^{2} > 0.$$

From (24) and (13), we have

$$MSE\left(\hat{y}_{\mathrm{R}HA}^{1}\right) - MSE\left(\hat{y}_{f}\right) = \frac{1-f}{n}\left(\rho S_{y} - \frac{3}{2}RS_{x}\right)^{2} > 0.$$

From (24) and (14), we have

$$MSE\left(\hat{\bar{y}}_{\sqrt{1}}\right) - MSE\left(\hat{\bar{y}}_{f}\right) = \frac{1-f}{n} \left(\rho S_{y} - \frac{1}{4}RS_{x}\right)^{2} > 0.$$

From (24) and (15), we have

$$MSE(\hat{y}_{\sqrt{2}}) - MSE(\hat{y}_{f}) = \frac{1-f}{n} \left(\rho S_{y} + \frac{1}{4}RS_{x}\right)^{2} > 0.$$

 Table 1. Parameters of Populations (Subramani and Kumarapandiyan [6])

Parameters	Population1	Population2	Population3
N	103	80	49
n	40	20	20
$ar{Y}$	62.6212	51.8264	116.1633
\bar{X}	556.5541	11.2646	98.6765
ho	0.7298	0.9413	0.6904
S_y	91.3549	18.3569	98.8286
C_y	1.4588	0.3542	0.8508
S_x	610.1643	8.4563	102.9709
C_x	1.0963	0.7507	1.0435

Table 2. Optimum values of d

	Population1	Population2	Population3
Value of d	1.76	2.06	1.94

5. Conclusion

From efficiency comparisons in Section 4 and the empirical results of the percentage relative efficiency of the proposed estimator \hat{y}_f with respect to the existing estimators \hat{y} , \hat{y}_R , \hat{y}_P , \hat{y}_R , \hat{y}_{Pe} , \hat{y}_{RHA} , $\hat{y}_{\sqrt{1}}$, and $\hat{y}_{\sqrt{2}}$ and in Table 2, we infer that the proposed estimator is more efficient and can produce better estimate than the mentioned existing estimators in the sense that it has least mean squared error..

Estimators		PRE of Proposed Estimator $\hat{\bar{y}}_f$	
	Population-1	Population-2	Population3
$\hat{\bar{y}}$	213.95	877.54	191.08
$ar{ar{y}}{\hat{ar{y}}_R}$	100.10	1317.99	154.93
$ar{y}_P$	569.48	8320.83	802.16
$\hat{ar{y}}_{Re}$	126.82	112.30	101.14
$\hat{ar{y}}_{Pe}$	361.50	3613.72	424.75
$\hat{ar{y}}_{RHA}$	133.79	4494.62	352.45
$\hat{\bar{y}}_{\sqrt{1}}$	162.84	248.56	128.14
$\hat{\bar{y}}_{\sqrt{2}}^{\sqrt{1}}$	280.17	1999.27	289.95

 Table 3. PRE of Proposed Estimator over Existing Estimators

References

- Bhal, S. and R.K. Tuteja, Ratio and product type exponential estimator. Information and Optimization Sciences. 12,(1991) 159-163.
- [2] Khan, H. Sanaullah, A. Khan, M. S. and Siddiqi, A. F. Improved Exponential Ratio Type Estimators for Estimating Population Mean Regrating Full Information in Survey Sampling Scheme. Sci. Int. (Lahore), 26(5), (2014) 1897-1902
- Singh, H. P., & Espejo, M. R. On linear regression and ratio-product estimation of a finite population mean. The Statistician, 52, (2003)5967.
- [4] Solanki, R. S., Singh, H. P. and A. Rathour (2012), An alternative estimator for estimating the finite population mean using auxiliary information in sample survey. ISRN Probability and Statistics, Volume 2012: dio:10.5402/2012/657682.
- [5] Singh, V. K. and Shukla, D. One parameter family of factor type ratio estimator, Metron, 45, 1-2, p. (1987)273-283.
- [6] Subramani, J. and Kumarapandiyan, G. Variance estimation using median of the auxiliary variable, International Journal of Probability and Statistics 1 (3) (2012) 3640.